



An Evolutionary Algorithm Approach to Generate Distinct Sets of Non-Dominated Solutions for Wicked Problems

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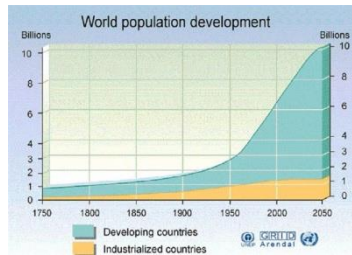
UTSA Water Resources Systems Analysis Lab:

PROBLEMS

Sustainability of the Built and Natural Environments



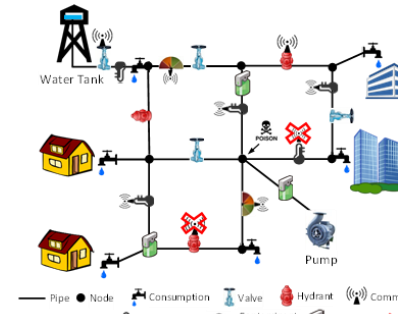
Drought Management and Water Conservation



Stormwater Management and Green Infrastructure



Resilience and Security of Cyber-Physical Systems



TOOLS

Simulation Models

Hydrologic and Hydraulic
Water Networks
Land Use Change
Population Growth

Optimization Algorithms

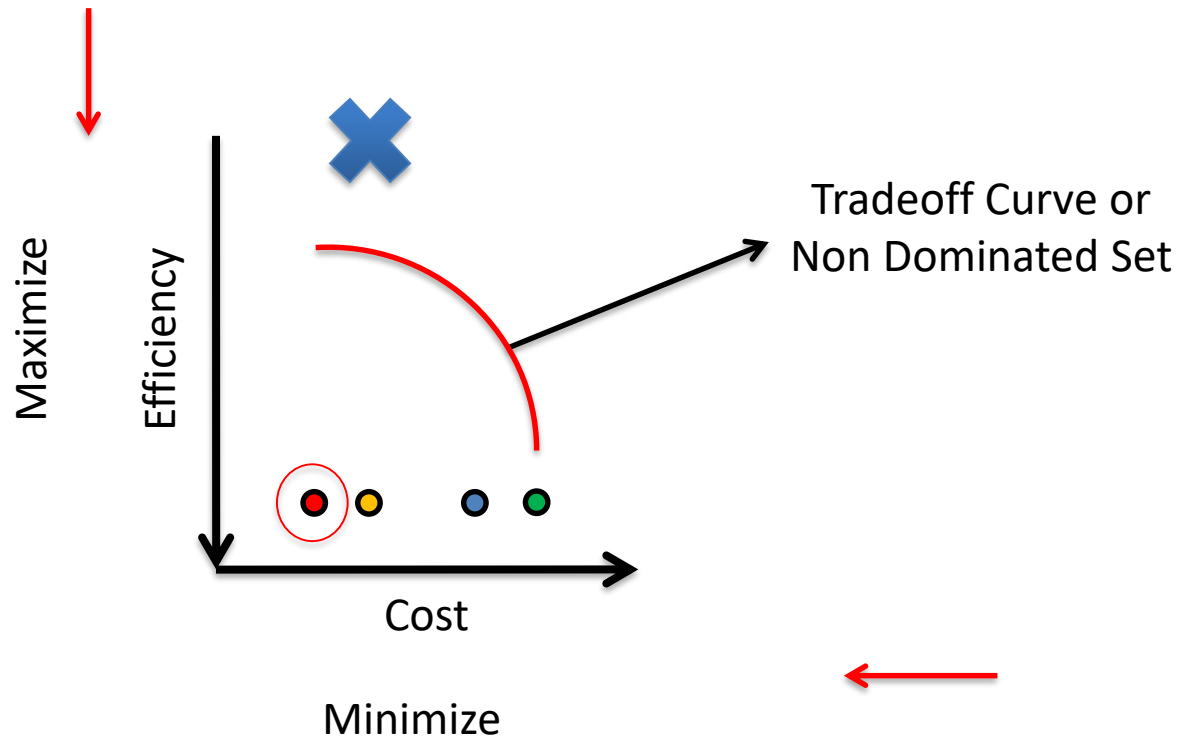
Evolutionary Computation
Single/multi-objective problems
Method for Generating
Alternatives

Data Collection and Analysis

GIS and Remote Sensing
Monitoring

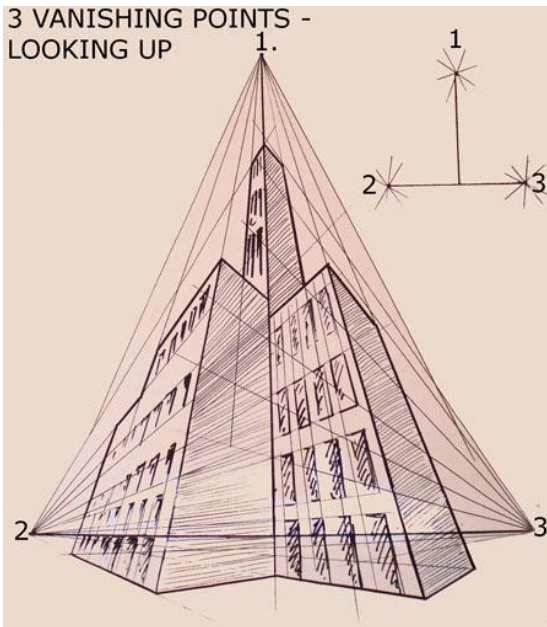
Engineering Problems

- Many engineering problems have multiple objectives:
 - Pareto front should be identified to represents the trade-off among conflicting objectives



Engineering Problems

- Real world problems are ill-posed:
 - Multiple perspectives (social, environmental, political)
 - Some objectives are difficult to model mathematically



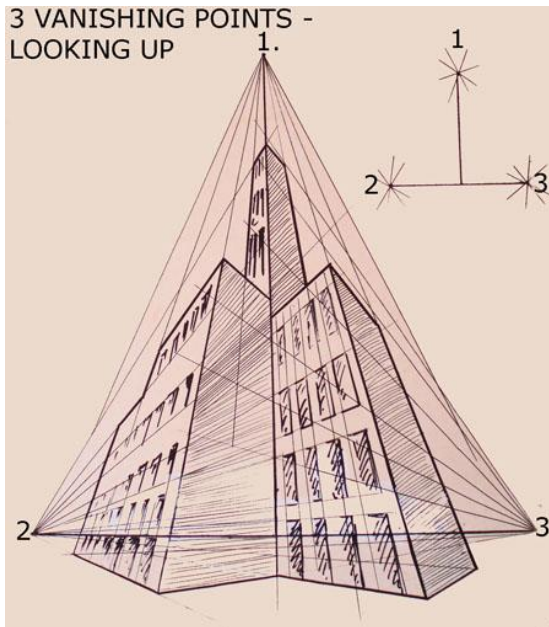
It's White
and
Gold!!!

No it's
NOT!!! It's
Blue and
Black!!!



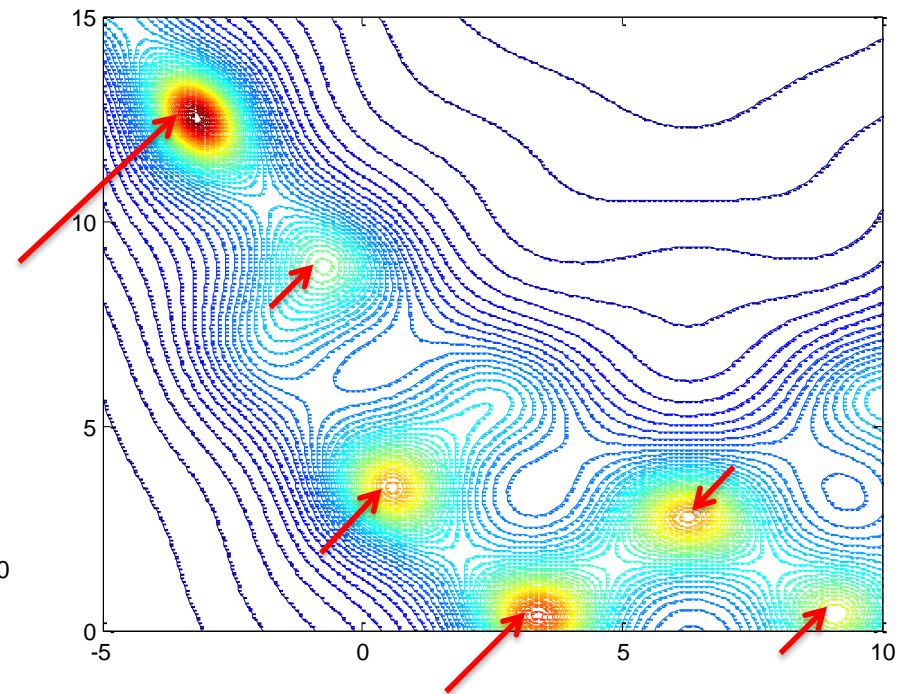
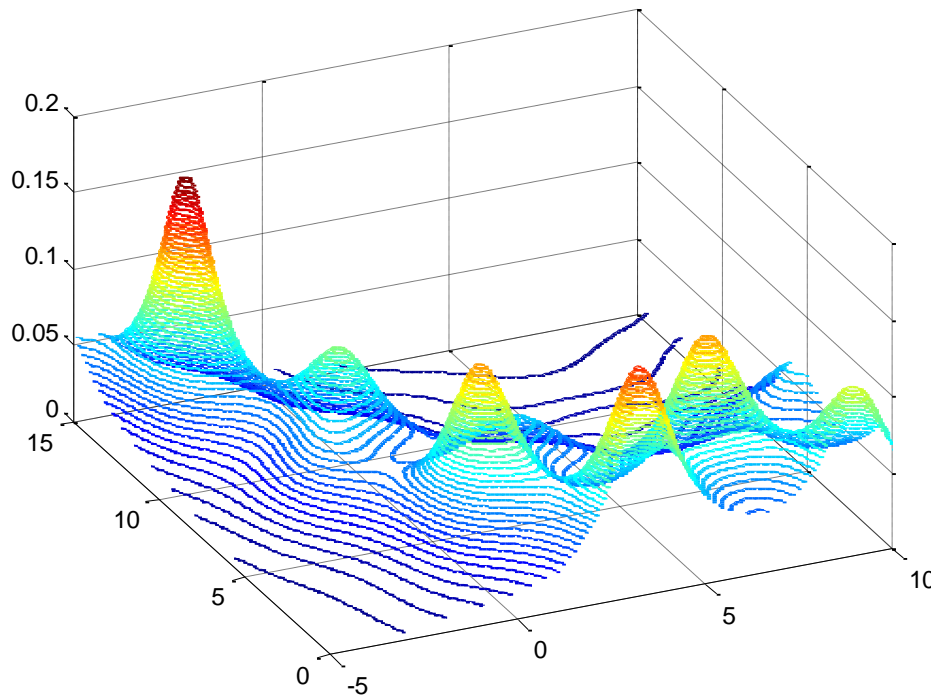
Engineering Problems

- Real world problems are ill-posed:
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 - Some objectives are difficult to model mathematically



Engineering Problems

- The fitness landscapes for realistic problems, are often non-linear, complex, and multi-modal.



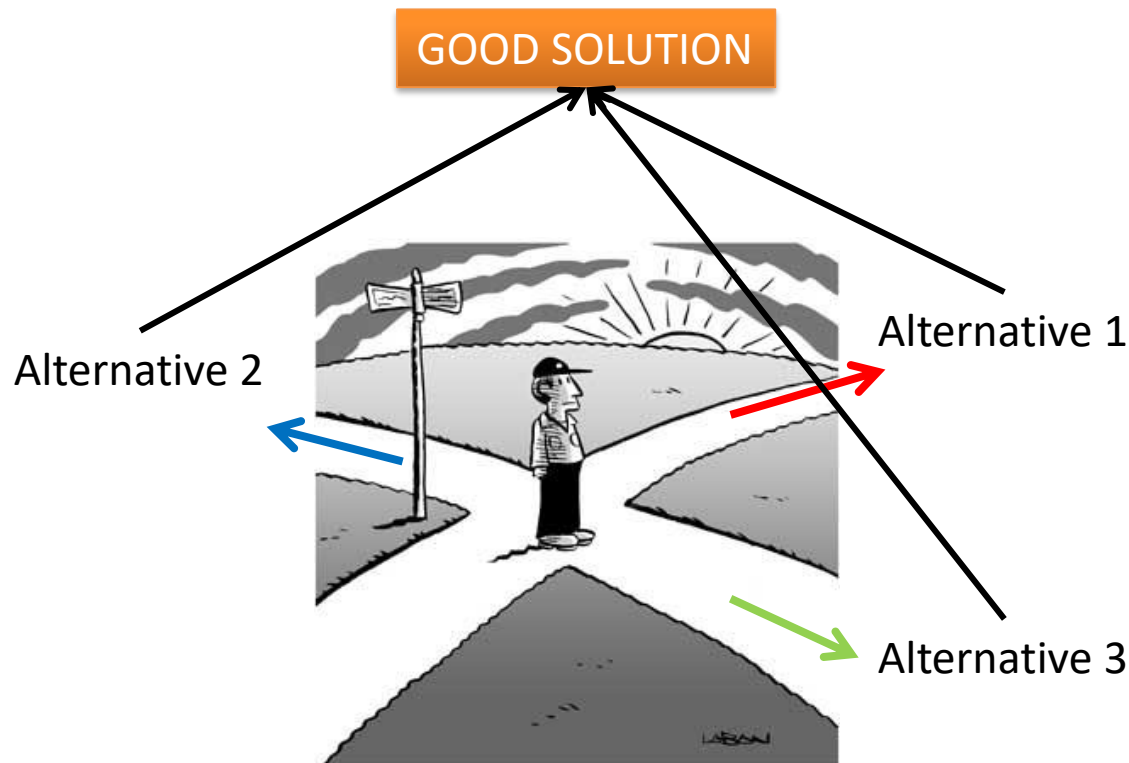
1

$$\text{Maximize } z = f(x, y) = \frac{1}{[a(y - bx^2 + cx - d)^2 + e(1 - f) \cos(x) \cos(y) + \log(x^2 + x^2 + 1) + e]}$$

$$x \times y \in [-5, 10] \times [0, 15] \quad a = 1; b = \frac{5.1}{4\pi^2}; c = \frac{5}{\pi}; d = 6; e = 10; f = \frac{1}{8\pi}$$

Modeling to Generate Alternatives

- Decision making can be aided through identification of alternative solutions



Modeling to Generate Alternatives

Original Problem:

Maximize $Z_k = f_k(X) \quad \forall k = 1, \dots, K$. (K – number of objectives)
Subject to $g_i(X) \leq b_i \quad \forall i = 1, \dots, M$. (M – number of constraints).

Optimal Solution:

X^* , with objective values of Z_k^*

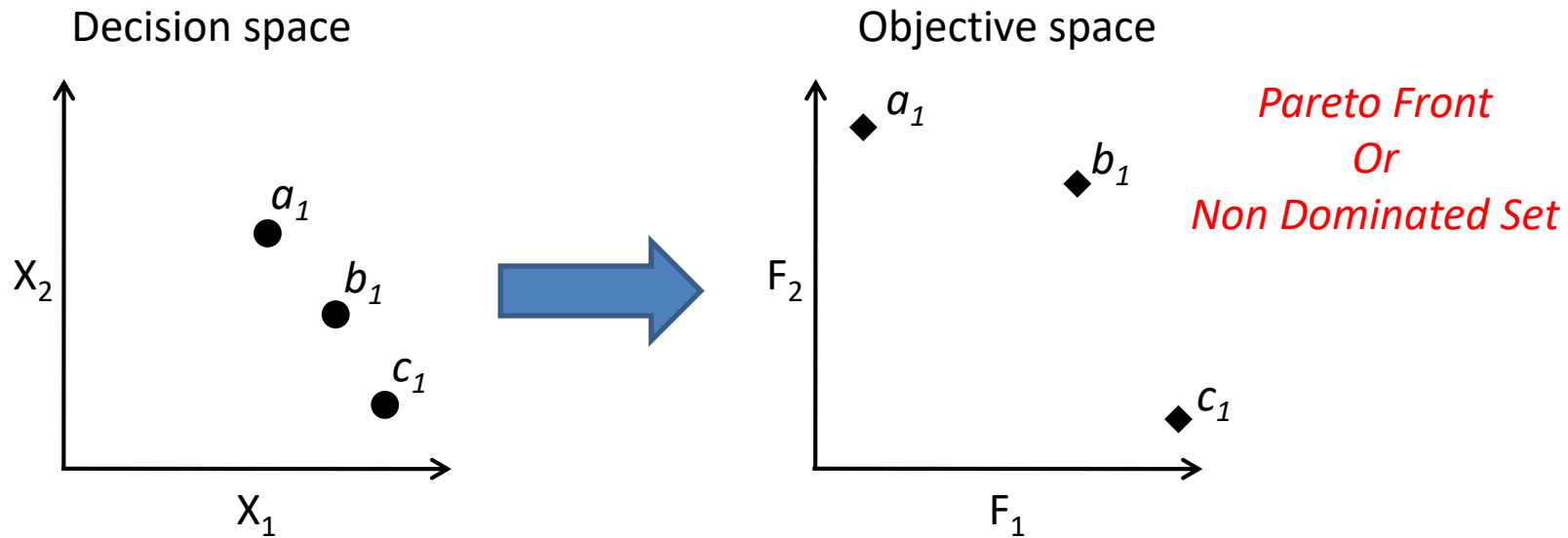
New Optimization Problem:

Maximize $D = \sum_j |x_j - x_j^*|$.
Subject to $g_i(X) \leq b_i \quad \forall i = 1, \dots, M$.
 $f_k(X) \geq T(Z_k^*)$.

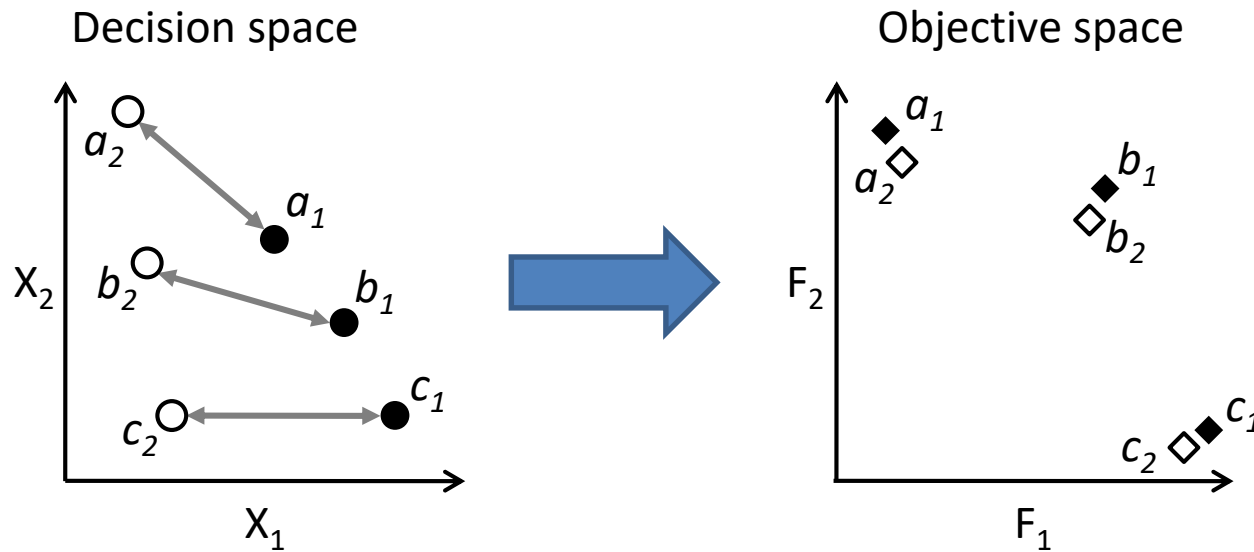
Research objective

- Develop an algorithm to identify a set of alternative Pareto fronts that are made up of solutions that map to similar regions of the **objective space** while mapping to **maximally** different regions of the **decision space**.

Multi-objective problems



Multi-objective multi-modal problems



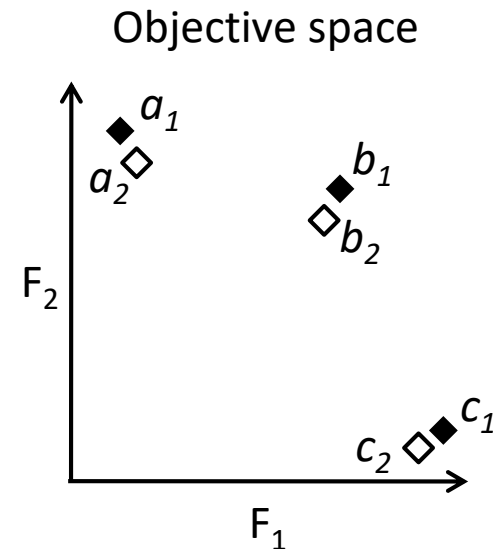
Two Sets of non-dominated solutions:

Pareto Front 1 - (a_1 , b_1 , and c_1)

Pareto Front 2 - (a_2 , b_2 , and c_2)

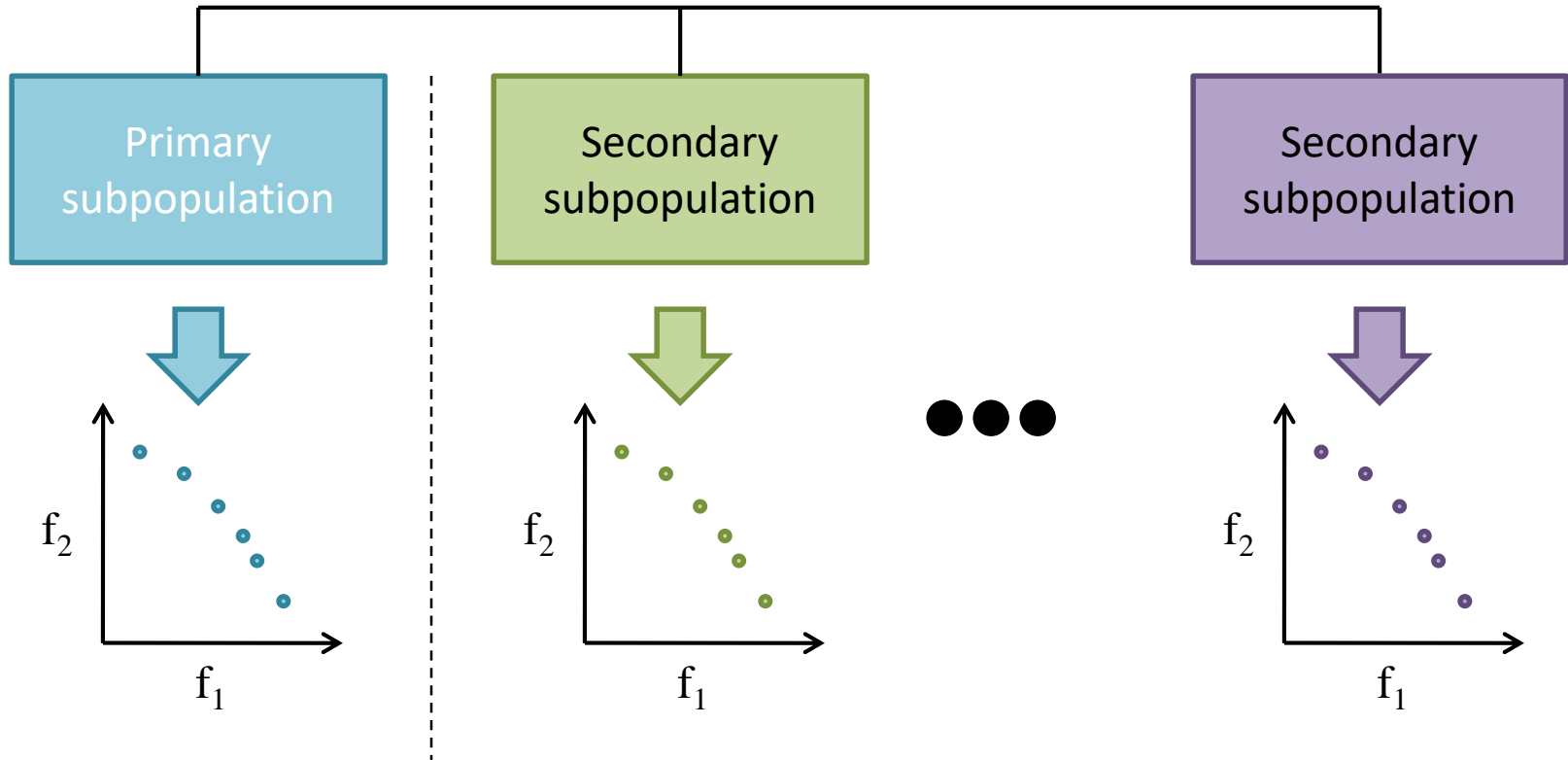
Multi-objective Evolutionary Algorithms to Generate Alternative Non-dominated Sets

- Use a set of populations to converge to alternative sets of non-dominated solutions
 - Each subpopulation will evolve one Pareto front that is different in decision space from other subpopulations
 - First subpopulation executes a conventional MOEA to find a typical Pareto front
 - Secondary subpopulations find alternative Pareto fronts



Multi-objective Niching Co-evolutionary Algorithm (MNCA)

- Multiple sub-populations co-evolve to distinct sets of non-dominated solutions

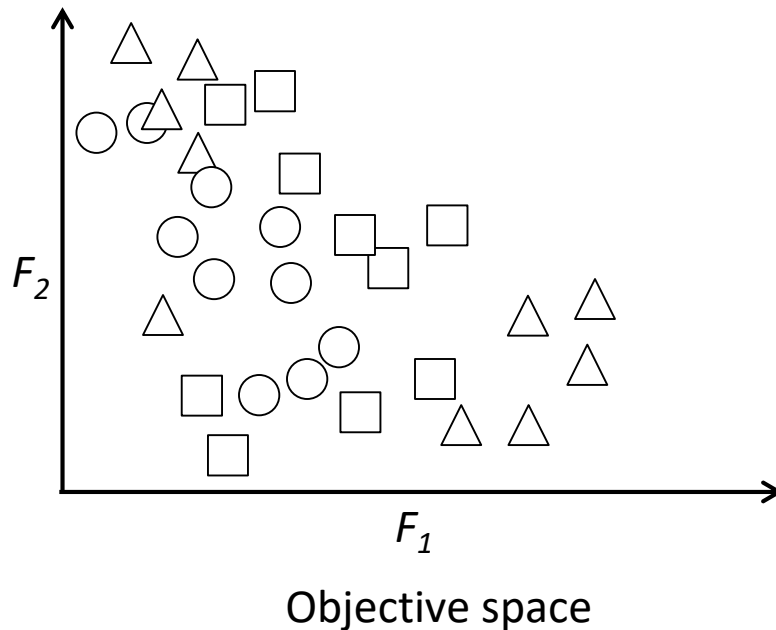


Multi-objective Niching Co-Evolutionary Algorithm (MNCA)

1. Group all solutions into clusters based on proximity in objective space
 - K-means clustering
2. Distance calculation
 - The distance of one solution is calculated in decision space to solutions that fall in the same cluster but in different subpopulations
3. Target Front
 - A target front is created, based on the first front of non-dominated solutions from first subpopulation
4. Feasibility Assignment
 - Label solutions in secondary subpopulations as feasible if they dominate any point in the target front
5. Selection:
 - First Subpopulation: NSGA-II operator
 - Secondary Subpopulations: Crowding Distance and Binary Tournament
 - Infeasible: rank and NSGA-II Crowding distance
 - Feasible: Crowding distance using four solutions

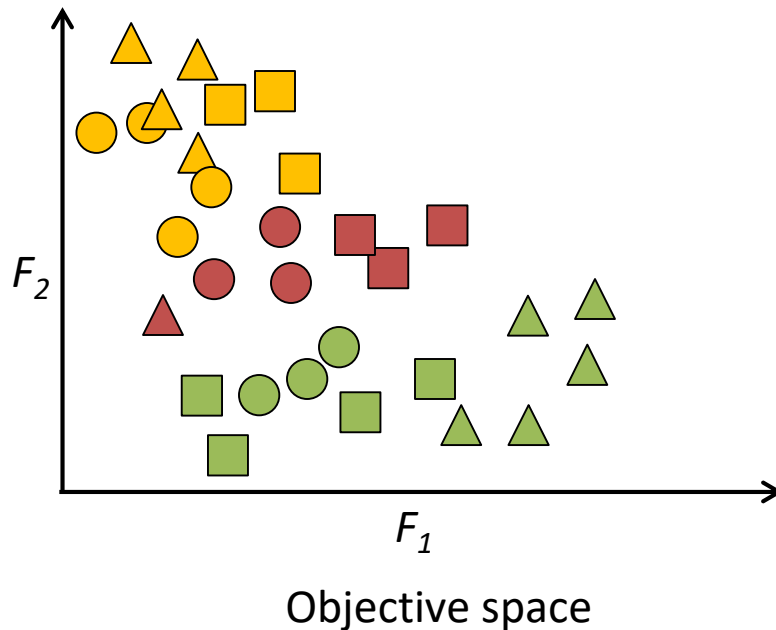
MNCA Algorithmic steps

1. Group all solutions into clusters based on proximity in objective space
 - K-means clustering



MNCA Algorithmic steps

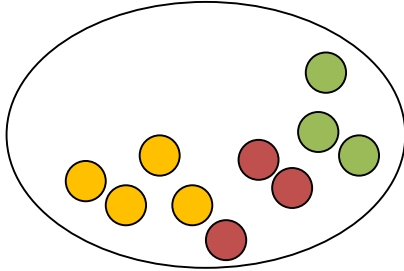
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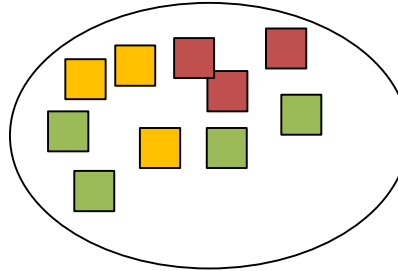
MCA Algorithmic steps

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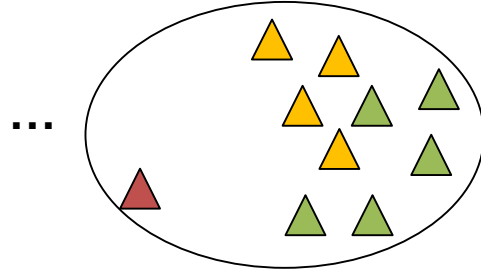
Subpopulation 1
SP₁



Subpopulation 2
SP₂



... Subpopulation SP_n



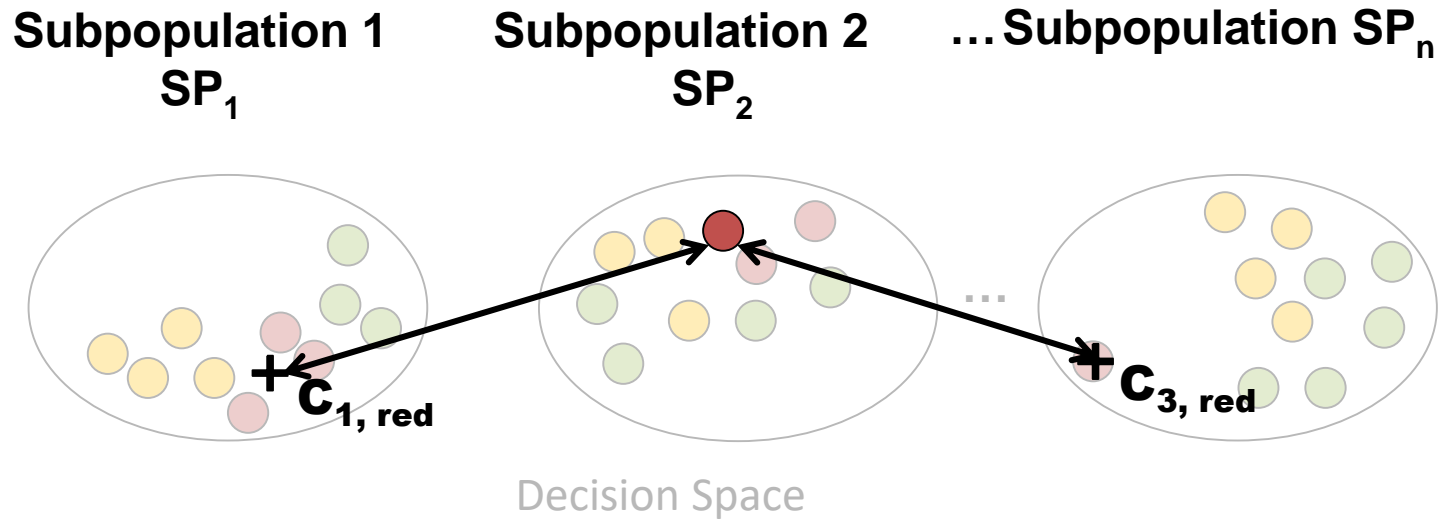
Decision Space

Colors represent different clusters that are formed based on similarities in objective space

MCA Algorithmic steps

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Distance calculation



Distance is calculated for each solution to centroid of same cluster in other subpopulations

Solution $Red_{2,i}$ Distance = minimum(Distance to $C_{1, red}$; Distance to $C_{3, red}$)

MNCA Algorithmic steps

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Target front

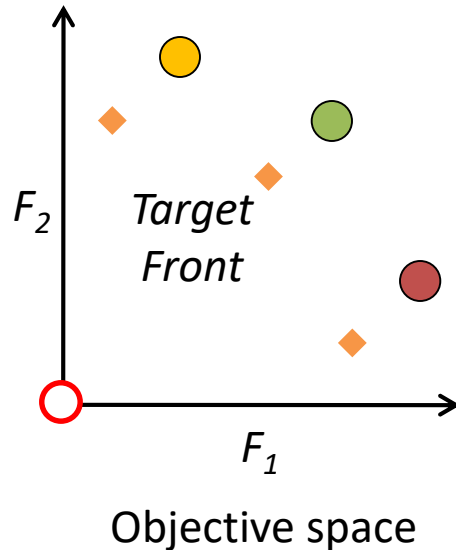
$$Z'_i = T(Z_i - WP_i) + WP_i$$

Z'_i is the a point on the target front

Z_i is the value of the i^{th} objective

T is the target reduction (i.e., 80%)

WP_i is the worst point for the i^{th} objective



MNCA Algorithmic steps

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Target front

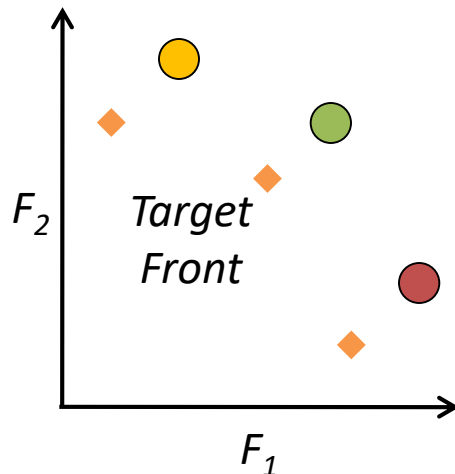
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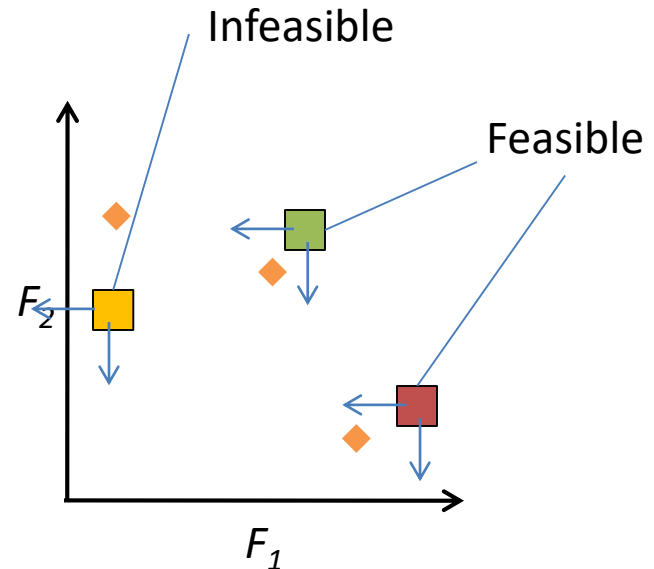
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Objective space



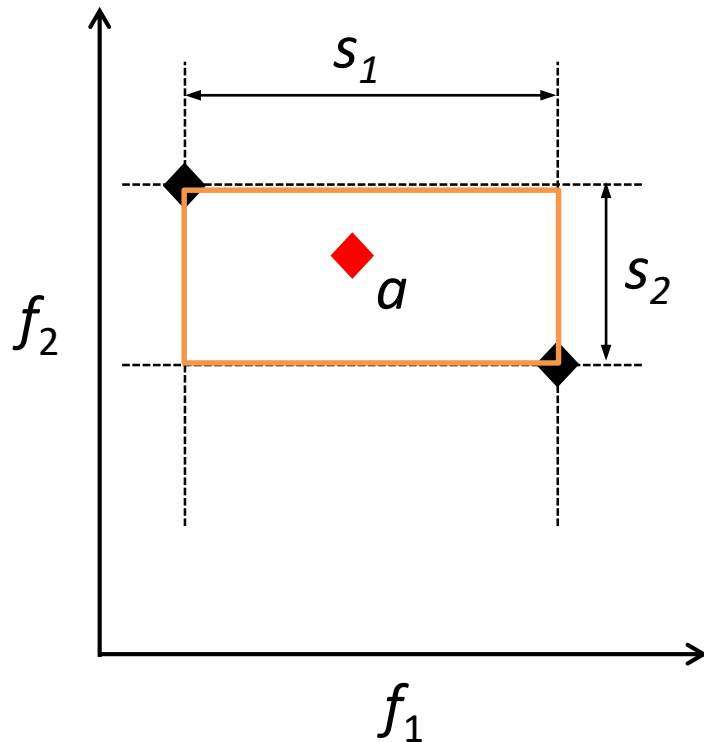
Objective space

MNCA Algorithmic steps

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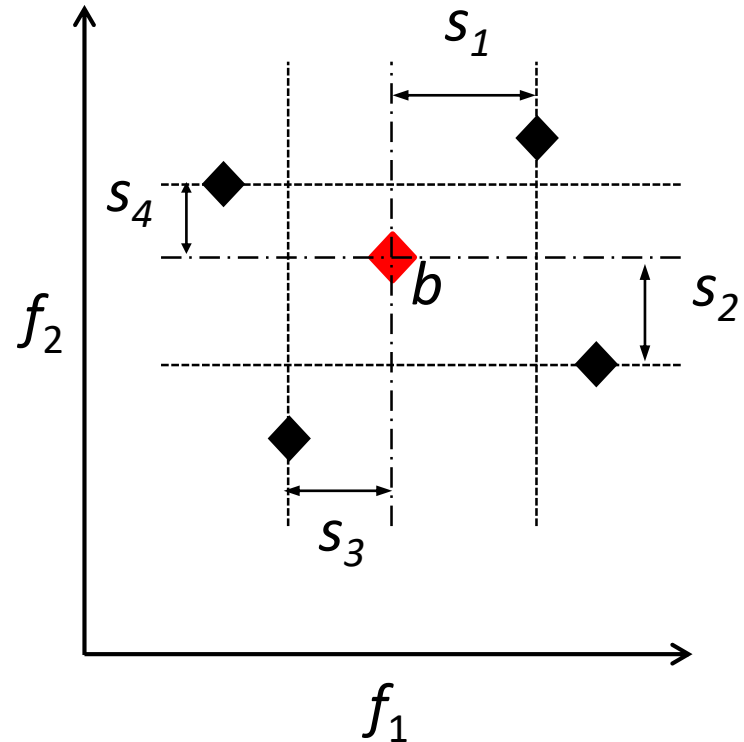
Crowding Distance

Infeasible Solutions



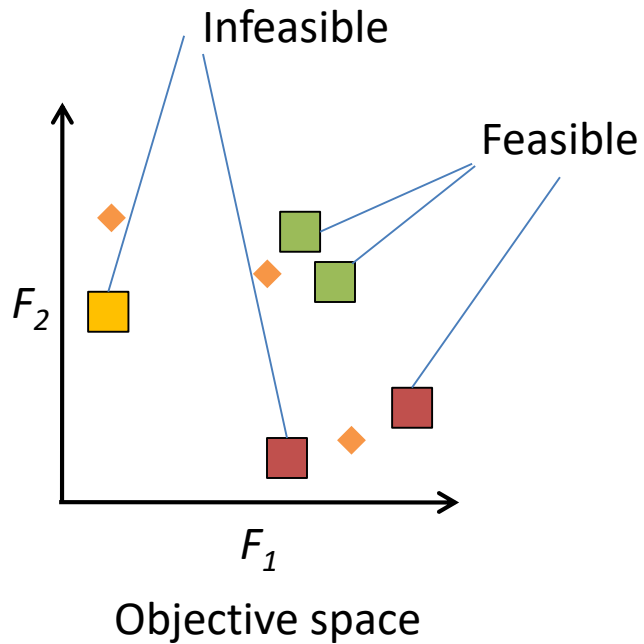
$$cd_b = \sum_{i=1}^2 s_i \quad (\text{NSGA-II})$$

Feasible Solutions



$$cd_a = \sum_{i=1}^4 s_i$$

Binary Tournament



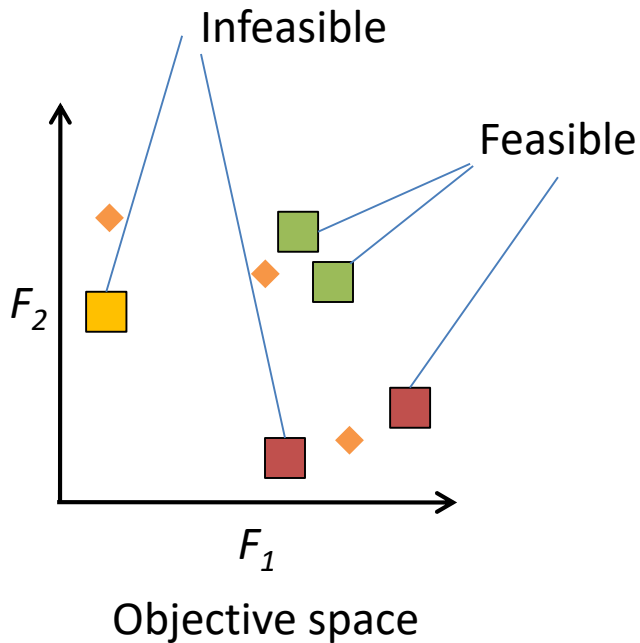
Infeasible

Feasible

X

Feasible WINS!!!

Binary Tournament

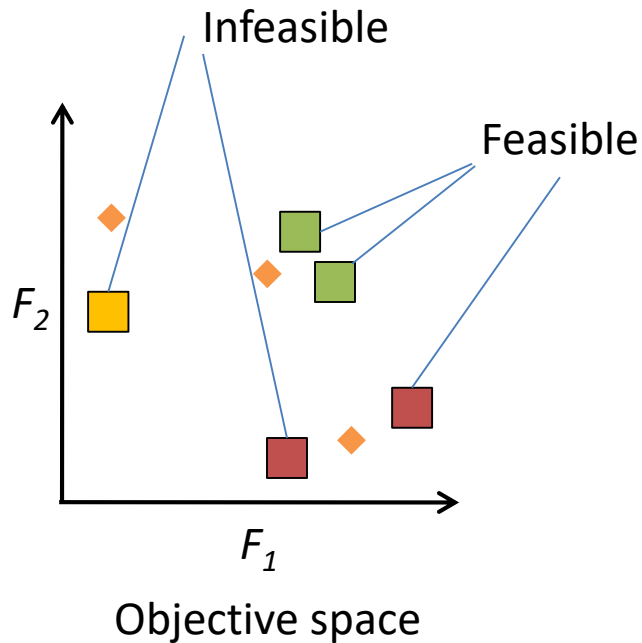


Feasible Feasible
Same Cluster
X

Higher Distance
WINS!!!

Solutions within the same region
of objective space:
Maximize Distance increasing
diversity.

Binary Tournament

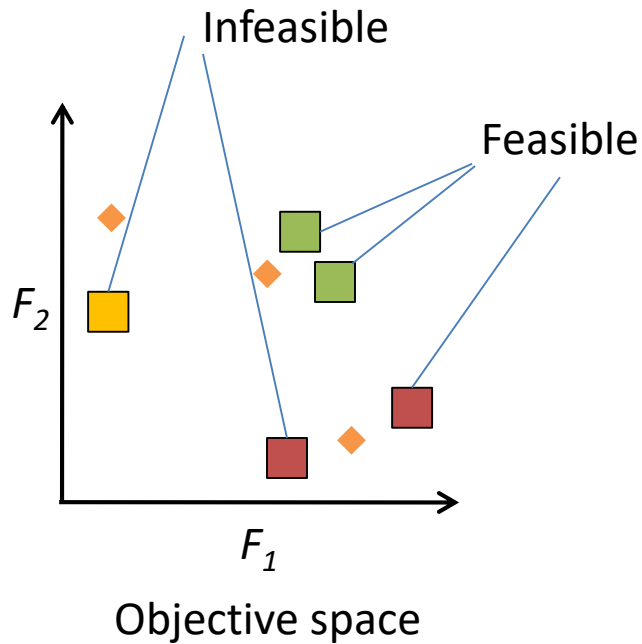


Feasible Feasible
Different Clusters
X

Higher Modified
Crowding Distance
WINS!!!

Solutions are from different parts
of the objective space:
pressure to improve the coverage
across the Pareto front.

Binary Tournament



Infeasible

Infeasible

X

Lower Front Rank or
Crowding Distance
WINS!!!

Niching-CMA

- Covariance Matrix Adaptation Evolution Strategy Niching Technique.
- Group solutions in niches based on their proximity in both decision and objective space.
- Outperformed other multi-objective and diversity-enhancing methodologies.

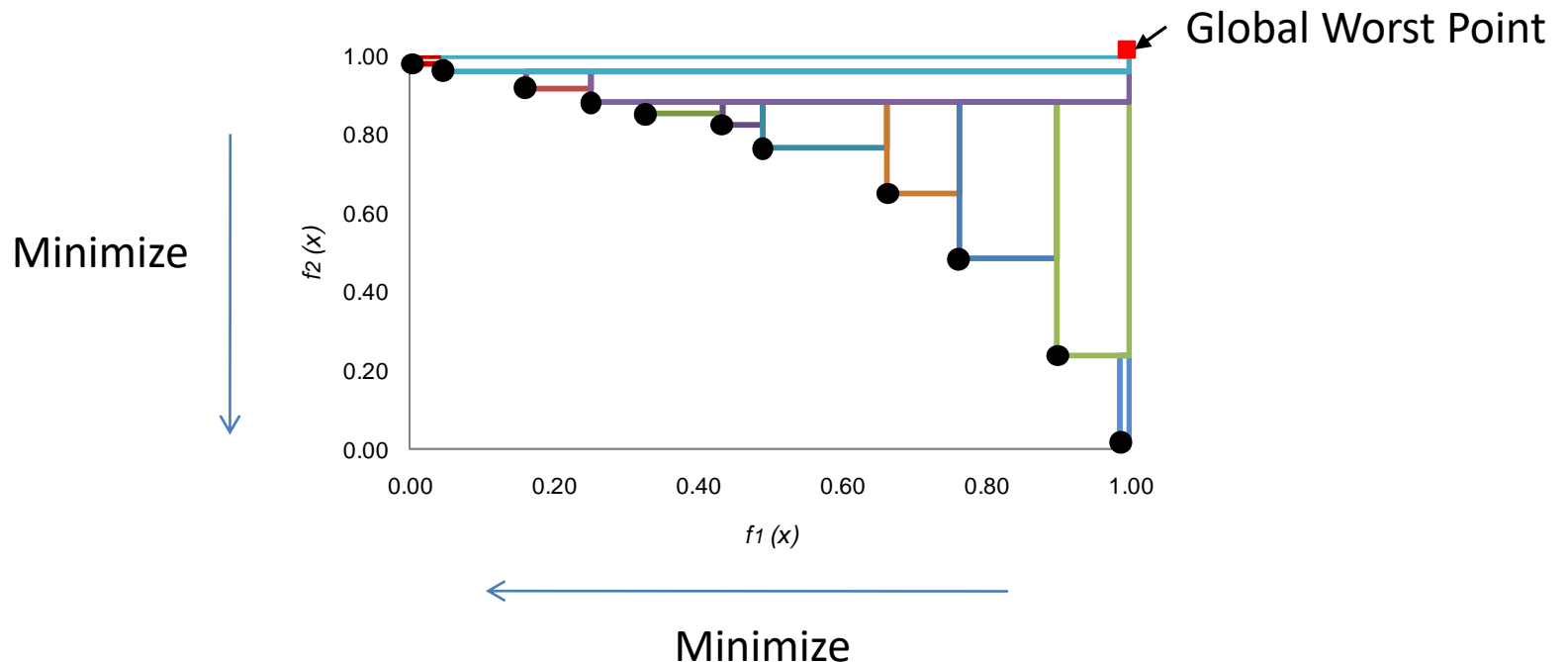
Algorithmic Settings

Parameter	Setting
Population Size	50
Subpopulations	2
Generations	1000
Mutation	1%
Clusters	5
Target	90% (95%) ¹

¹ 95% was used for the function Two-on-One

Hypervolume

- Represents the size of the space covered by the non-dominated set
- Used as an indicator to measure the quality of a non-dominated set



Decision Space Diversity

- Assess diversity in decision space based on the distance between all pair of individuals in a population
- Average of the distances between pairs of solutions and is normalized by the diameter of the decision space

$$\text{diversity} = \frac{1}{R \times \text{pop}(\text{pop}-1)} \sum_{i=1}^{\text{pop}} \sum_{j=i+1}^{\text{pop}} d(X_i, X_j) \quad (7)$$

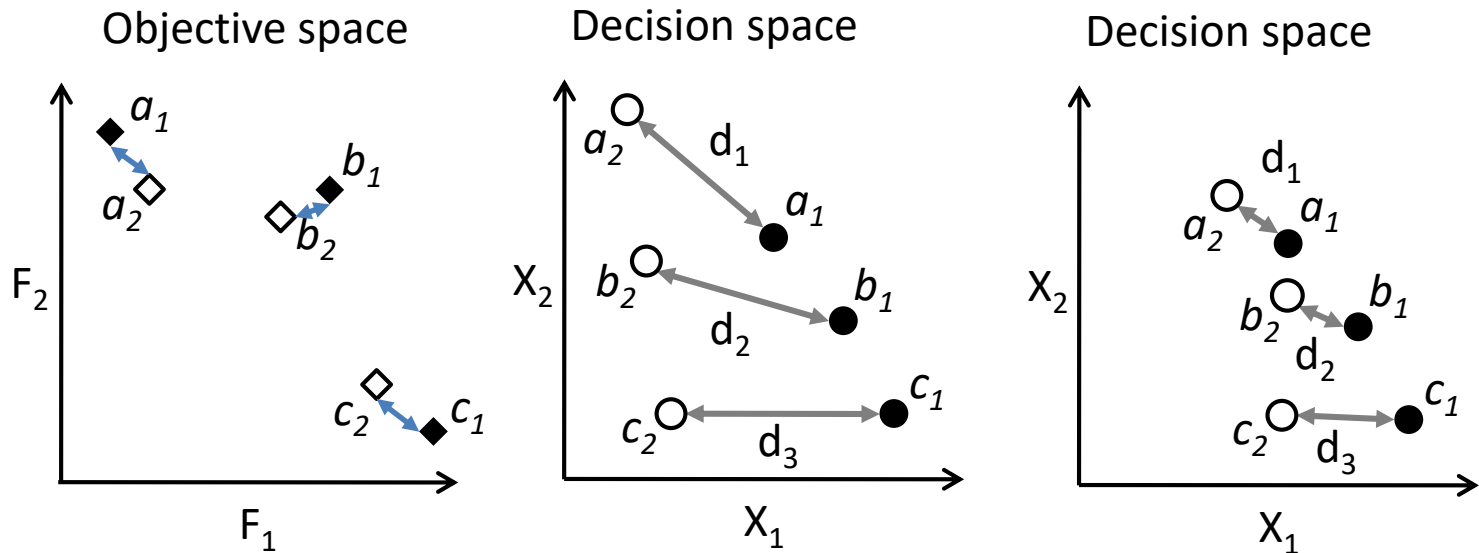
where $d(X_i, X_j)$ is the Euclidean distance in decision space between the i th and j th solutions in a subpopulation. The equation for R is given as

$$R = \sqrt{\sum_{i=1}^N (x_{i,\max} - x_{i,\min})^2} \quad (8)$$

Paired Solution Diversity

- New metric to assess set of solutions that are distant in decision space though similar in objective space.
- Pair solution of one subpopulation with solution of another subpopulation that is nearest in objective space, and for each pair, calculating the Euclidean distance in the decision space.

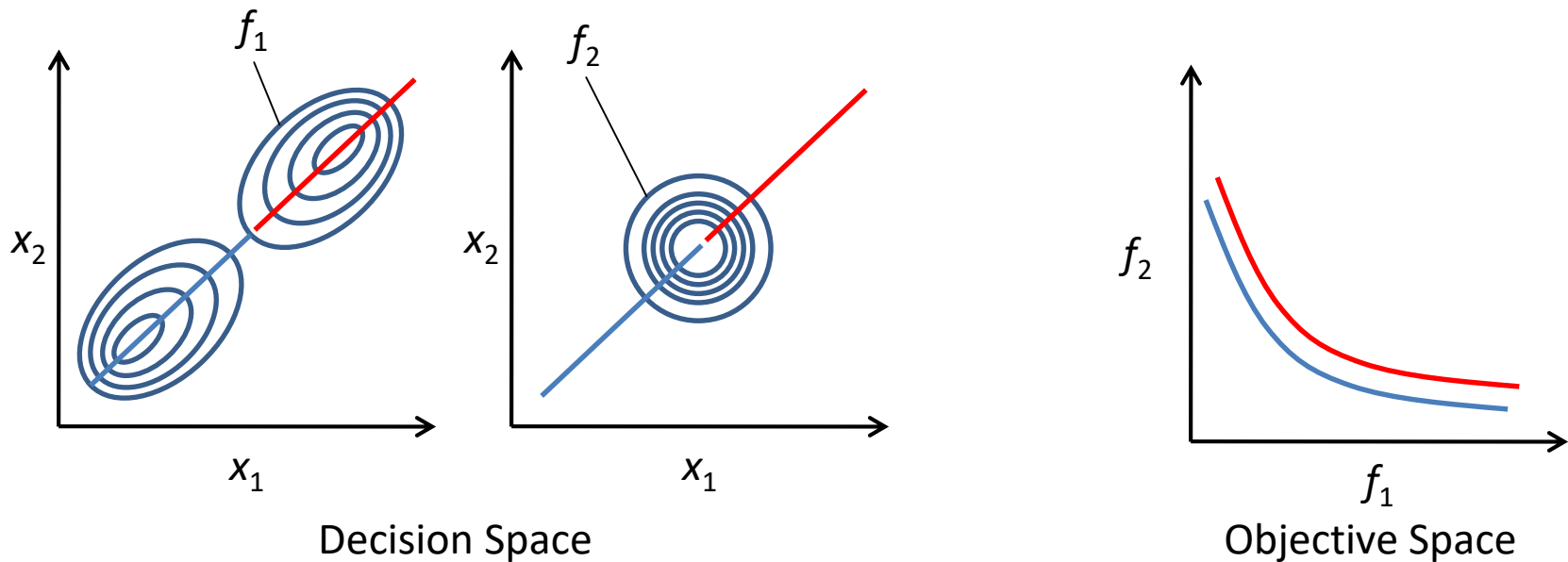
Paired Solution Diversity



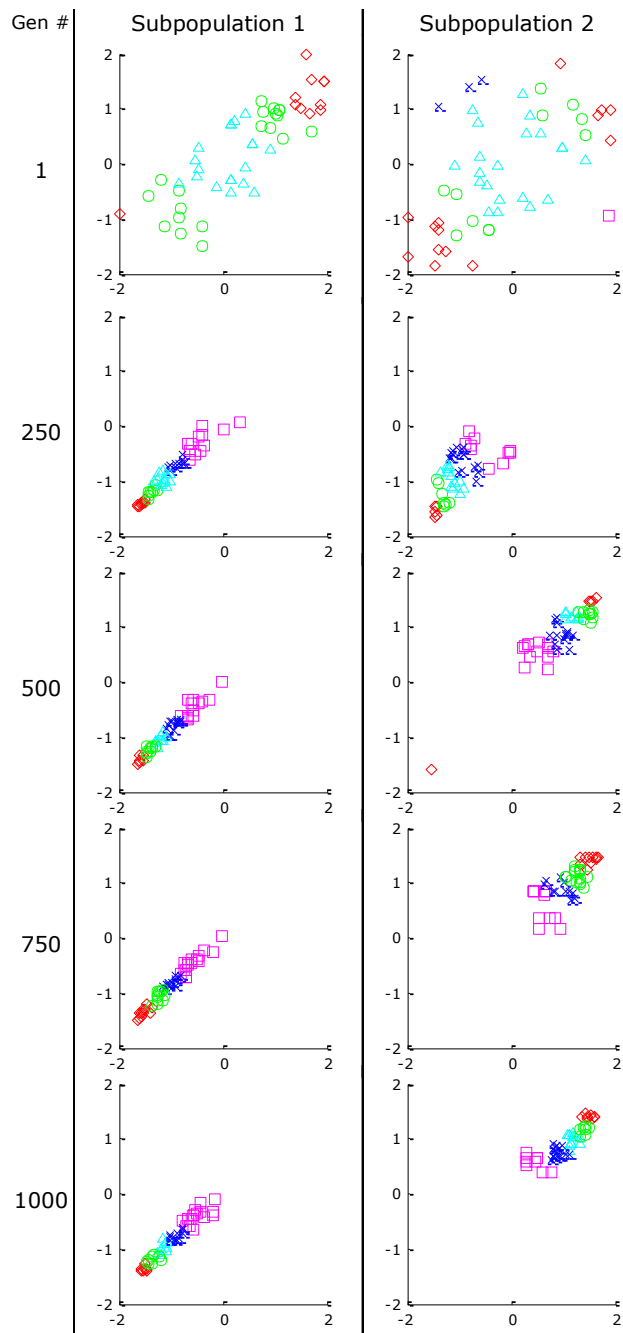
$$diversity_{ps} = \frac{d_1 + d_2 + d_3}{3}$$

Test Function Two-on-One

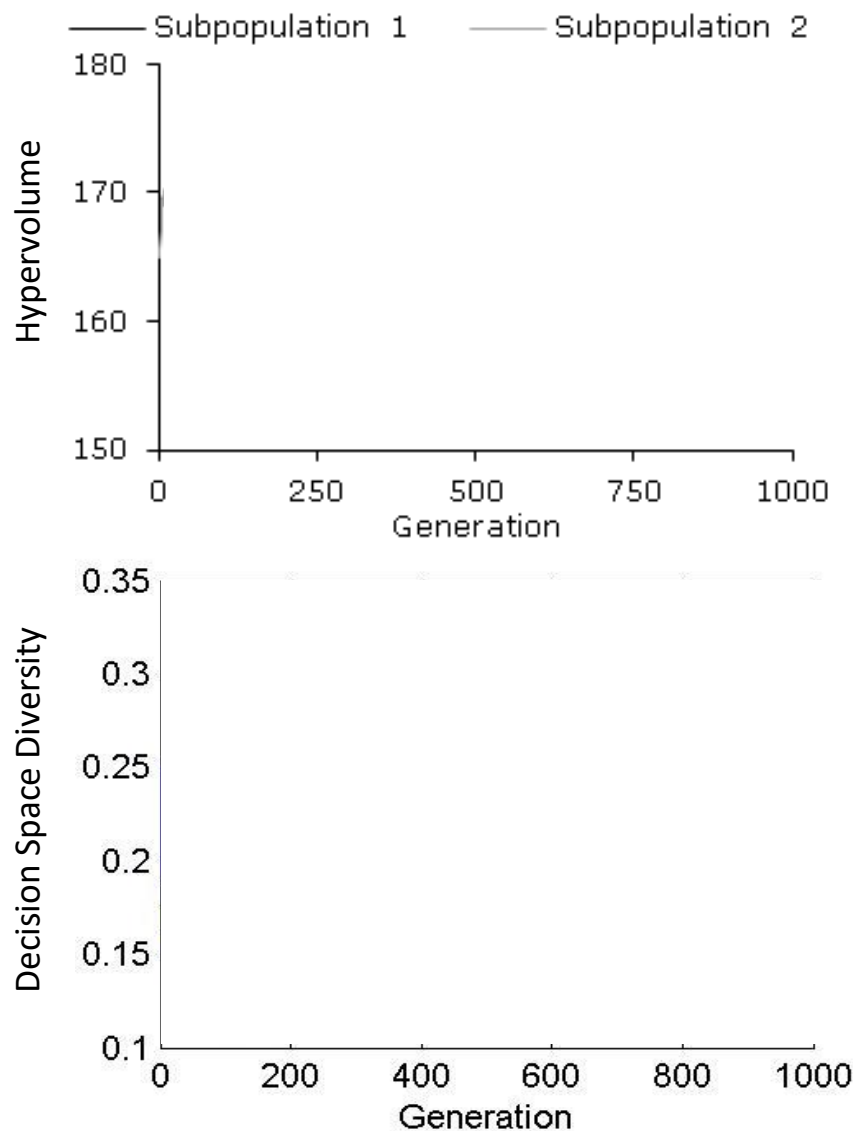
- Two-on-One is a bi-modal problem composed of a fourth degree polynomial with two optima and a second-degree sphere function.



Decision Space

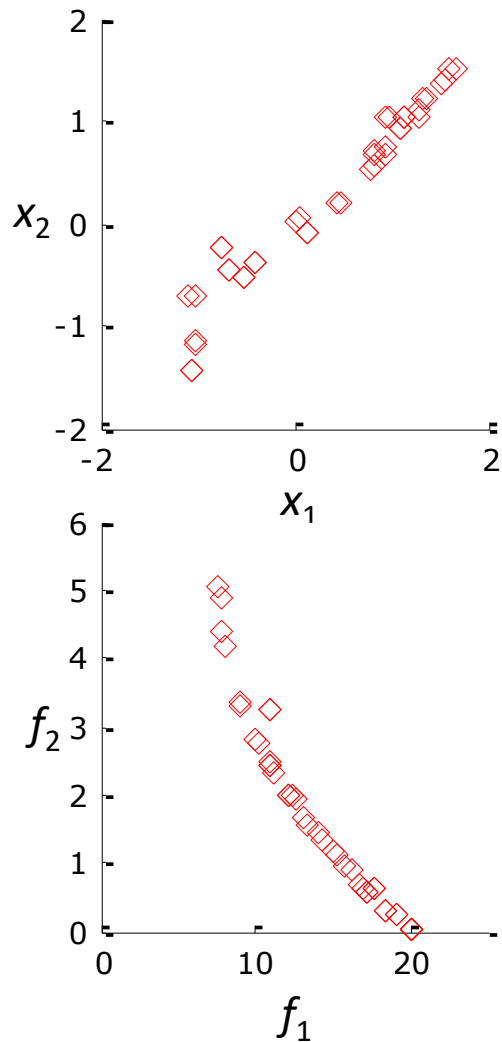


Function Two-on-One



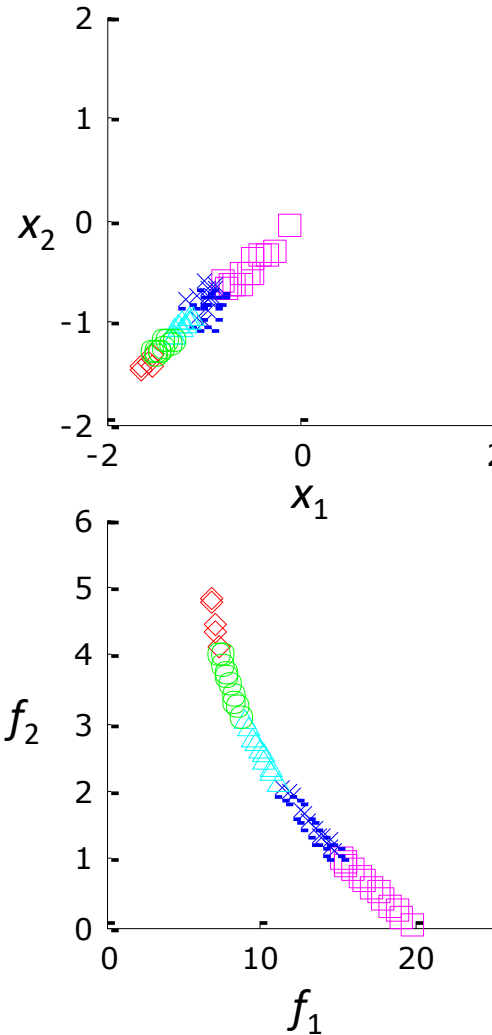
Function Two-on-One

Niching-CMA

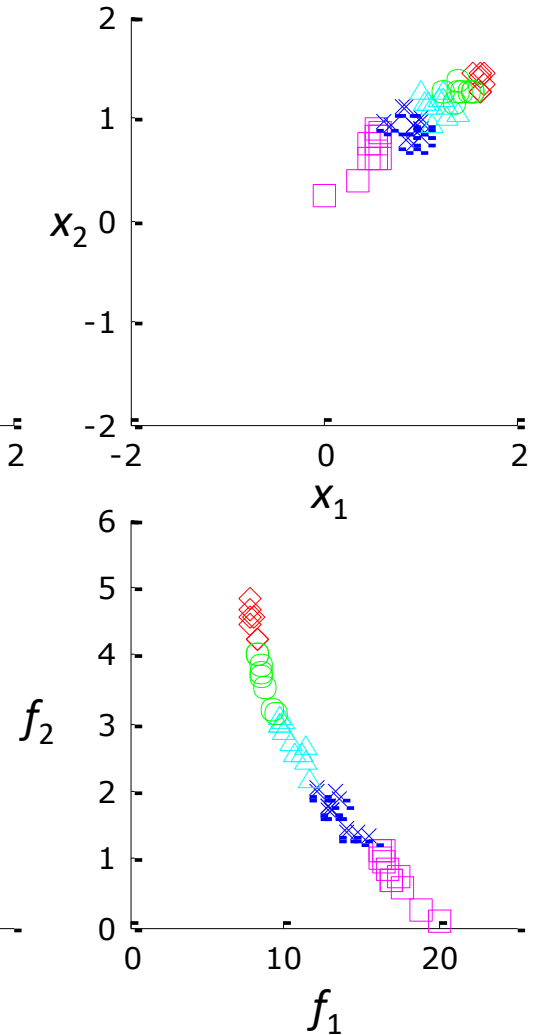


MNCA

Subpopulation 1

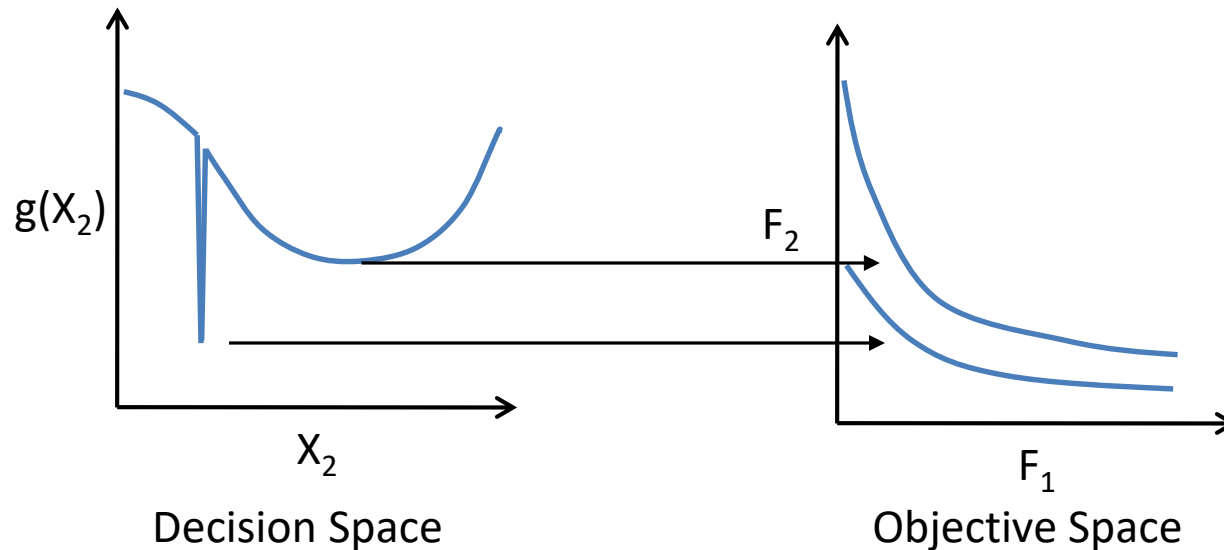


Subpopulation 2



Test Function Deb99

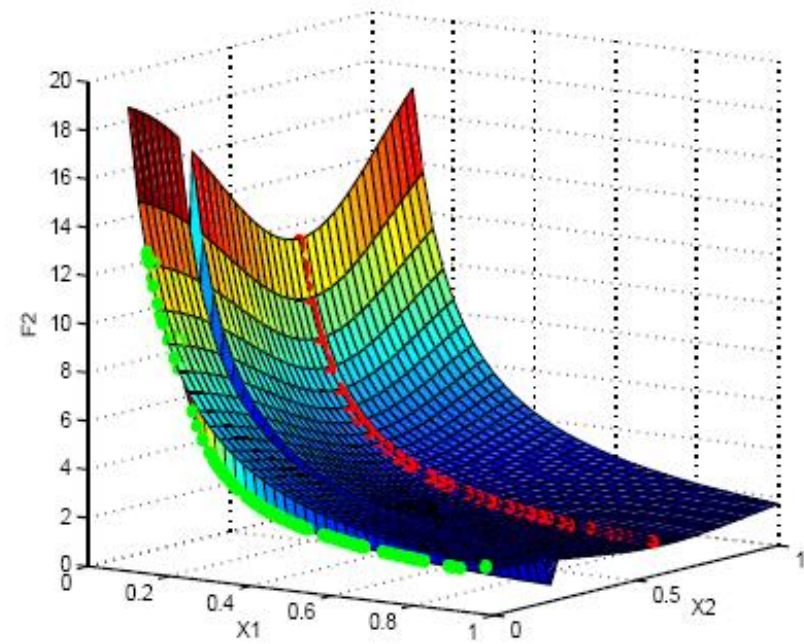
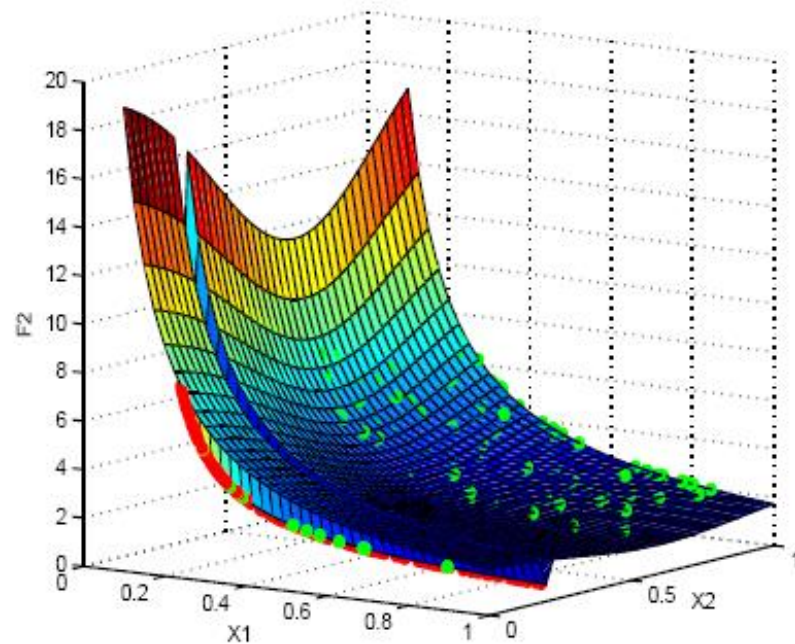
- Deb99 is a deceptive multi-objective problem that has a global optima difficult to identify and a local optima located in a long flat valley that is easy to find.



M. Preuss, B. Naujoks, and G. Rudolph, "Pareto Set and EMOA Behavior for Simple Multimodal Multiobjective Functions," in Parallel Problem Solving from Nature - PPSN IX, 2006, pp. 513–522.

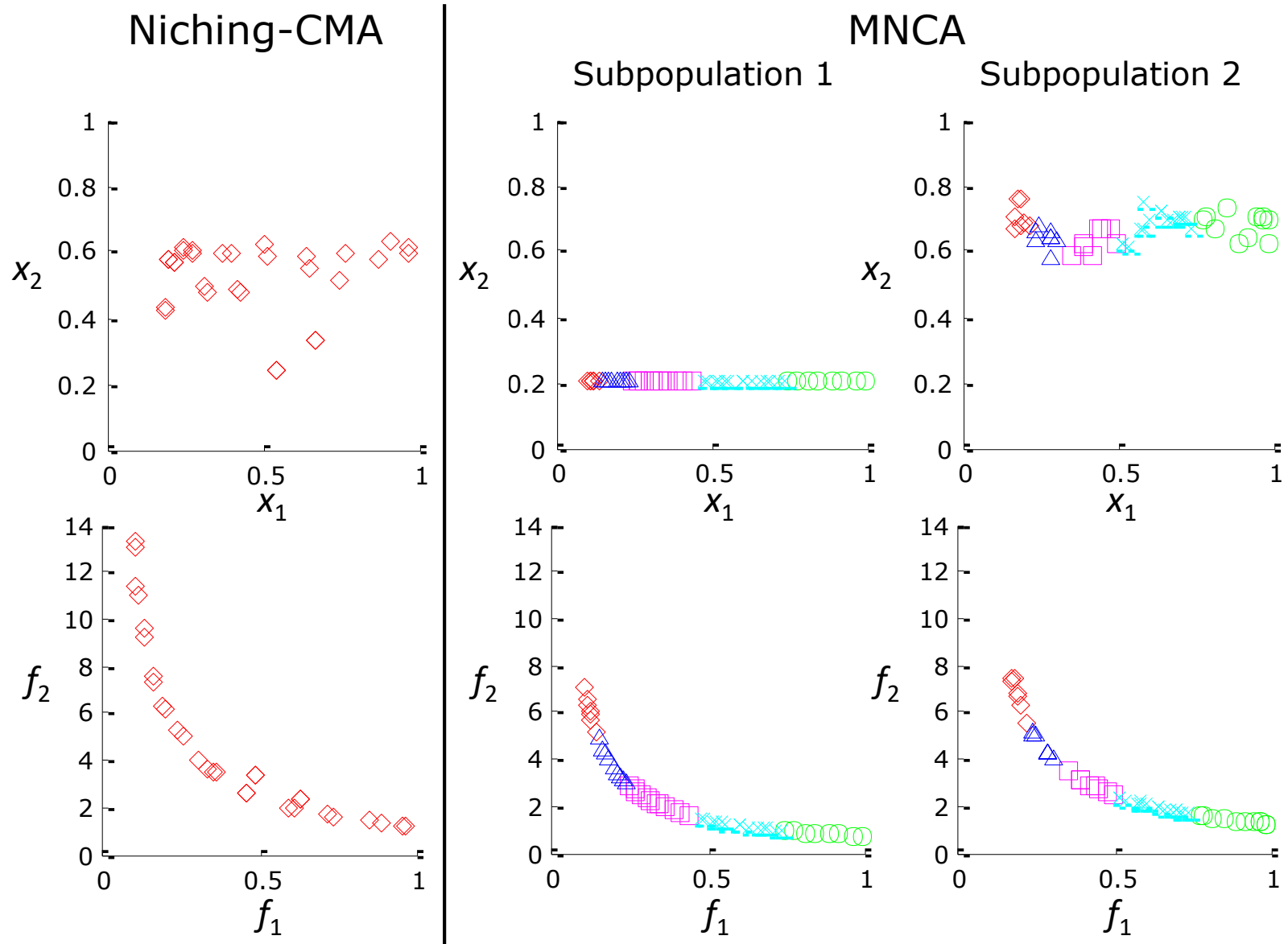
Deb99 Test Function

Deb99	Minimize $f_1 = x_1$; Minimize $f_2 = \frac{g(x_2)}{x_1}$	$0 \leq x_i \leq 1$
	$g(x_2) = 2 - \exp\left\{-\left(\frac{x_2 - 0.2}{0.004}\right)^2\right\} - 0.8 \exp\left\{-\left(\frac{x_2 - 0.6}{0.4}\right)^2\right\}$	$i = 1, 2$



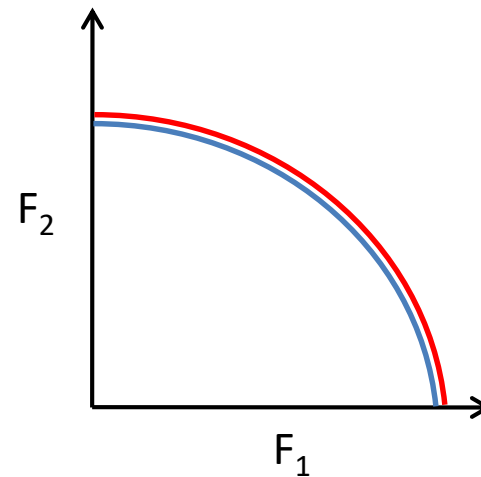
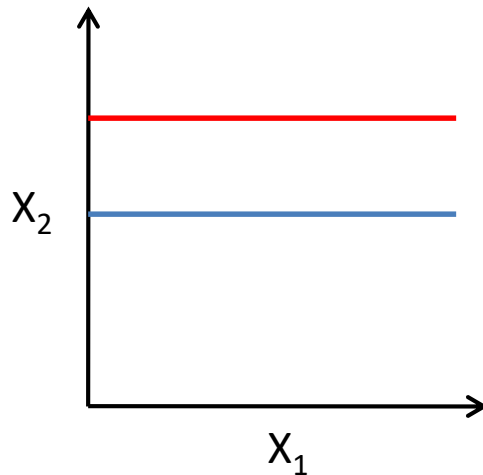
- First subpopulation
- Second subpopulation

Function Deb99

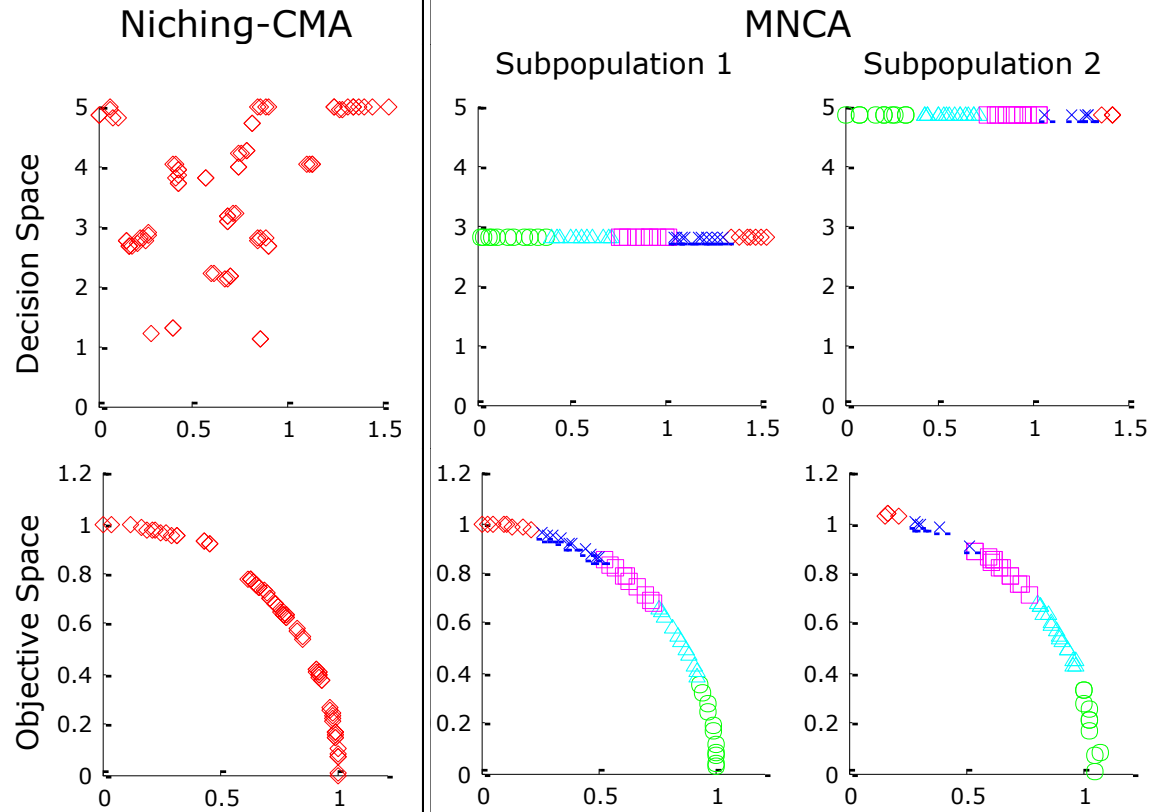


Lamé Supersphere

- Lamé Supersphere is a multi-modal problem global with spherical geometry in objective space and equidistant parallel lines in decision space.



Function Lamé Supersphere



Hypervolume

Test Function	Niching CMA	MNCA	
		Subpopulation 1	Subpopulation 2
Two-on-One	169.6 ± 1.9	173.6 ± 0.1	165.6 ± 3.2
Deb99	7.95 ± 0.69	9.12 ± 0.01	7.45 ± 0.35
Lamé Superspheres	3.12 ± 0.13	3.19 ± 0.02	2.95 ± 0.14

Decision Space Diversity

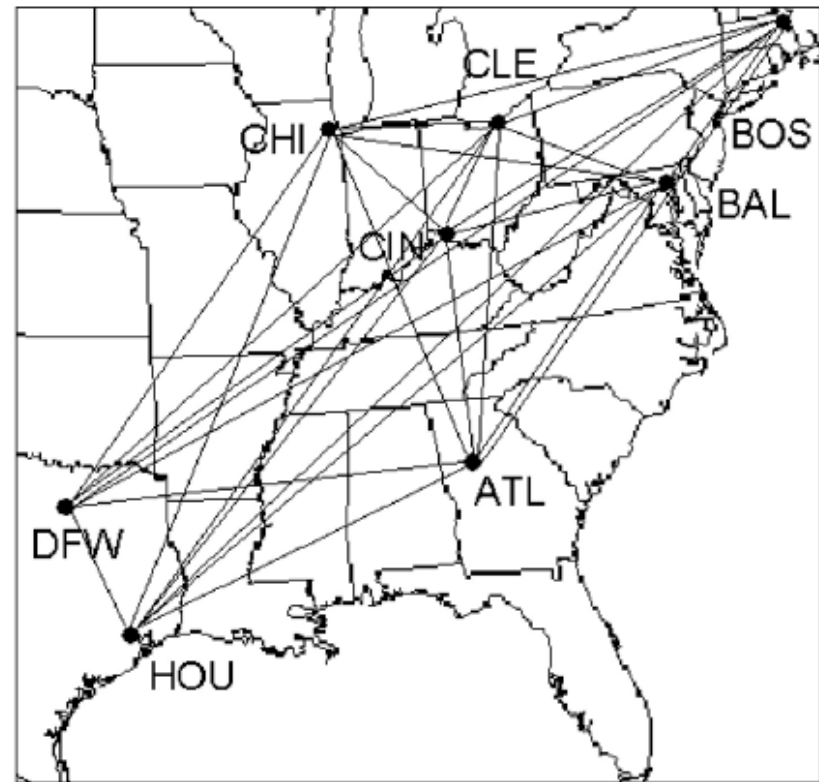
Test Function	Niching CMA	MNCA
Two-on-One	0.231 ± 0.031	0.298 ± 0.032
Deb99	0.285 ± 0.032	0.359 ± 0.015
Lamé Superspheres	0.329 ± 0.039	0.112 ± 0.007

Paired Solution Diversity

Test Function	MCA	MNCA
Two-on-One	2.158 ± 0.239	2.64 ± 0.49
Deb99	0.23 ± 0.06	0.47 ± 0.08
Lamé Superspheres	0.79 ± 0.05	1.59 ± 0.04

Realistic Planning Problem: Airline Routing

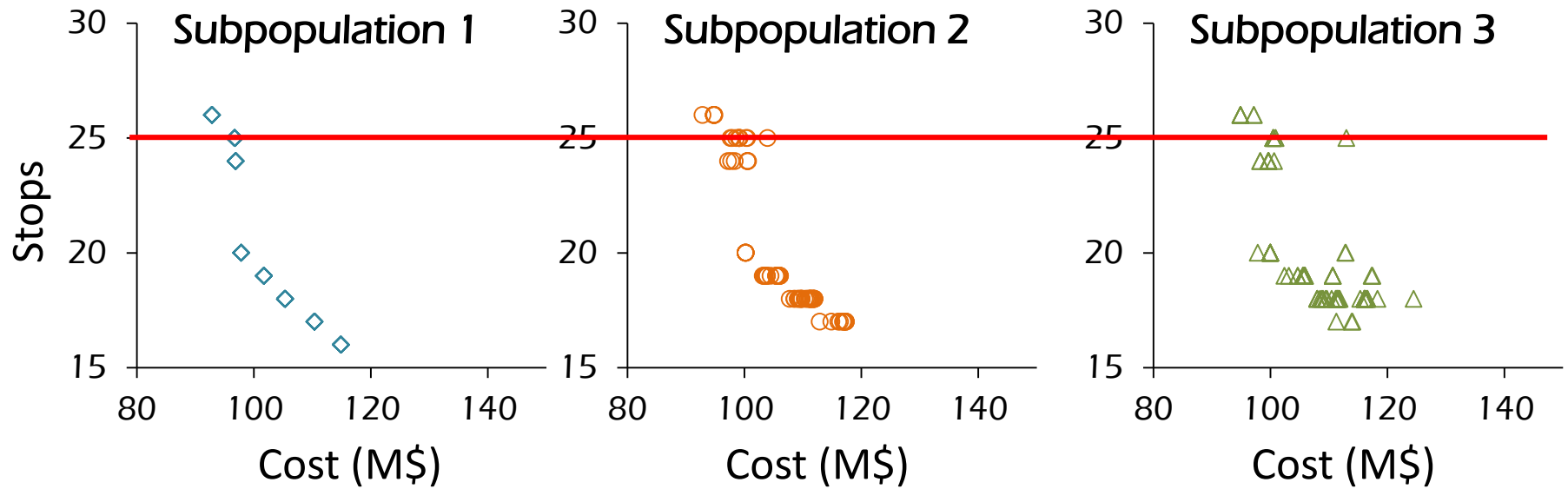
- Determine a set of 28 routes to connect 8 cities to maintain objectives:
 - minimize f_1 : Cost
 - minimize f_2 : Number of stops
- Given:
 - Number of requests at each city
 - Cost of initial set-up
 - Cost of each flight
 - Unit cost for each passenger
 - Potential type of connections:
 - Directly
 - Indirectly- through multiple-leg connections



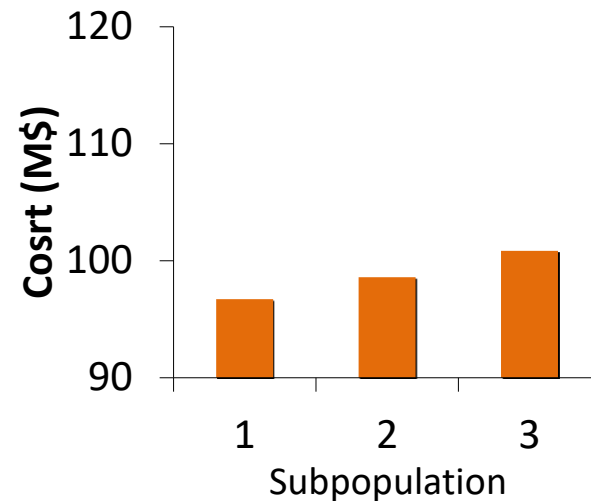
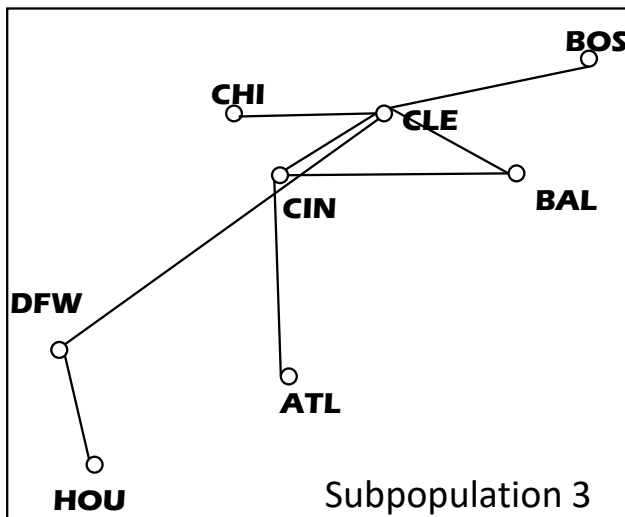
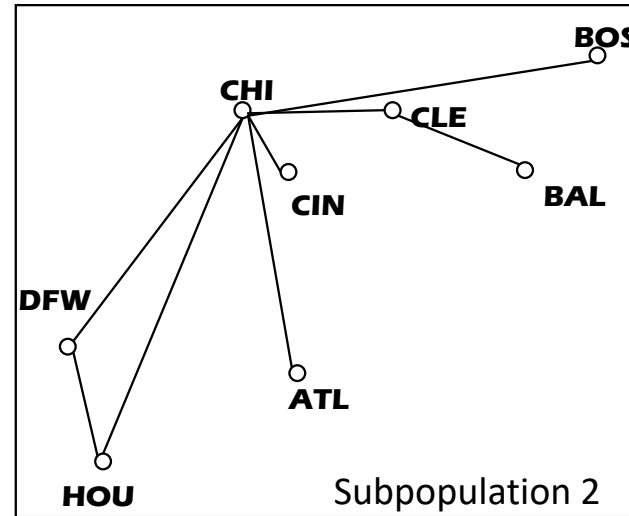
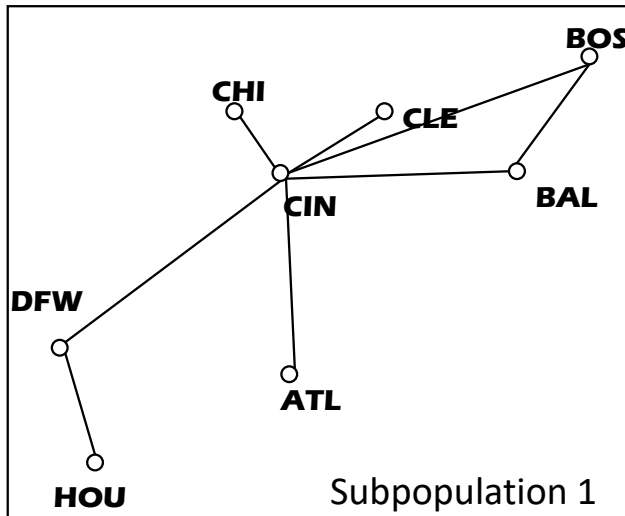
Settings for MNCA

Parameter	Setting
Population Size	100
Subpopulations	3
Generations	100
Mutation	1%
Clusters	5
Relaxation coefficient	90%

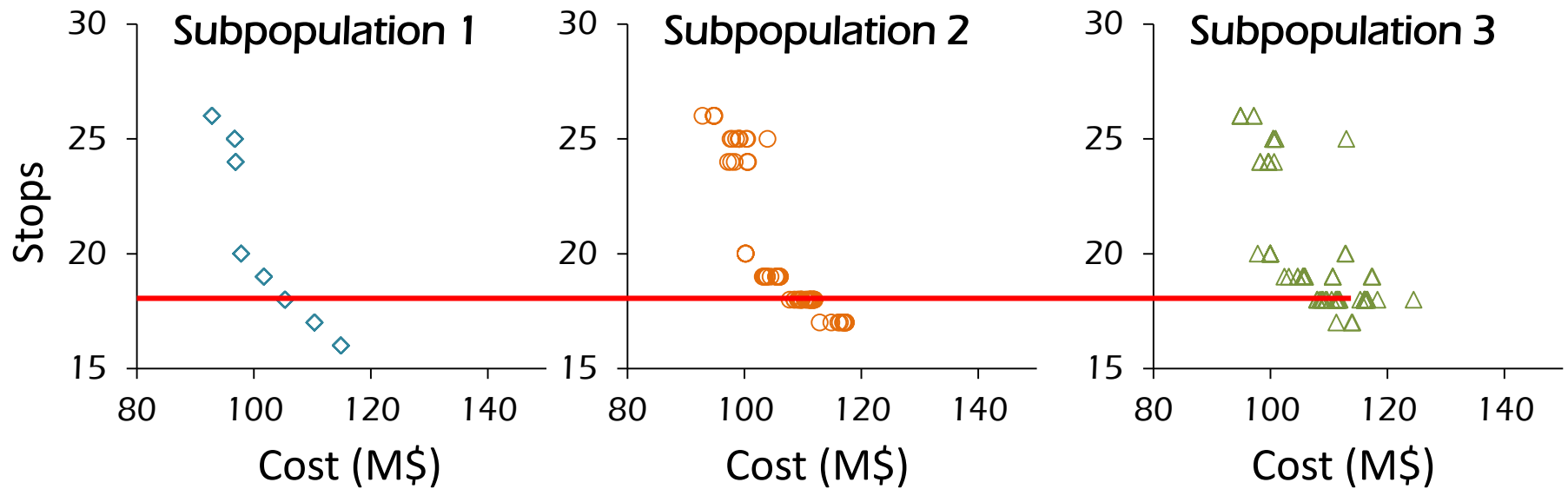
Distinct sets of non-dominated solutions



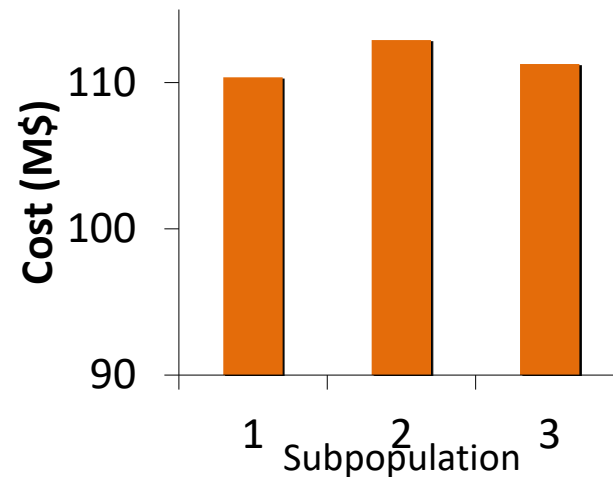
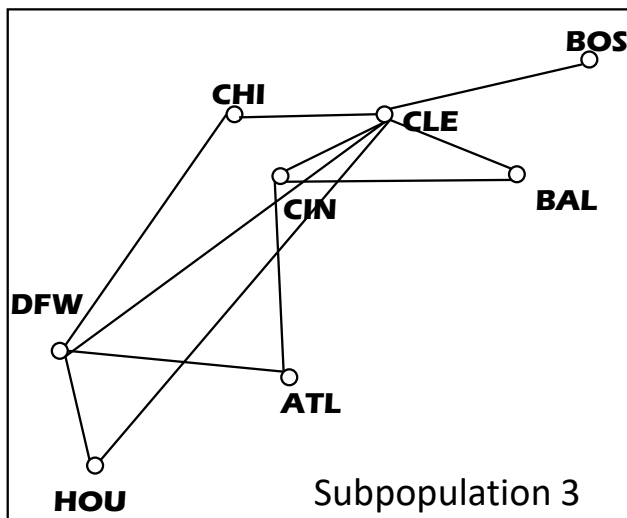
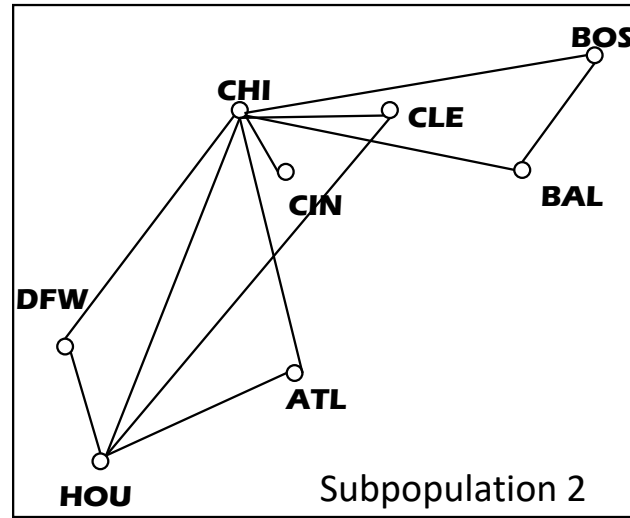
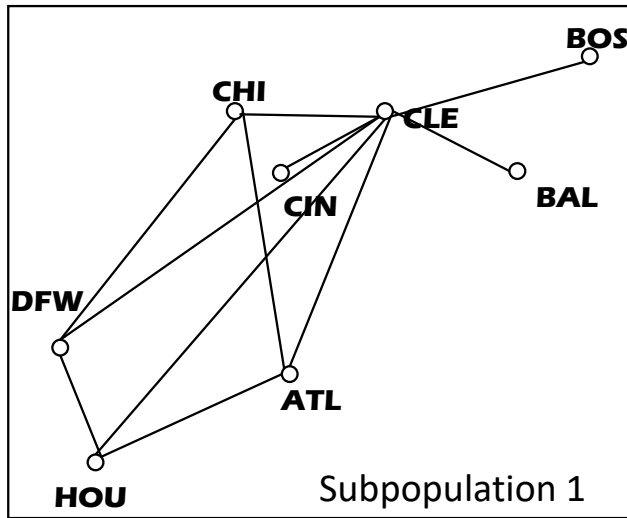
Twenty five-stop alternative solutions



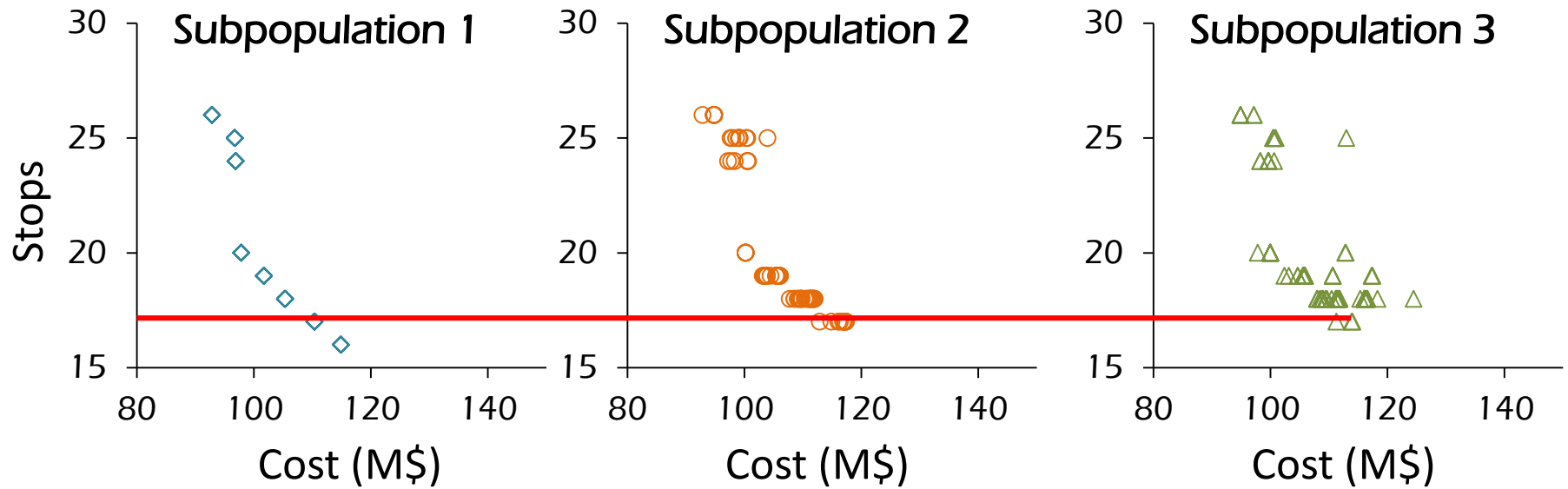
Distinct sets of non-dominated solutions



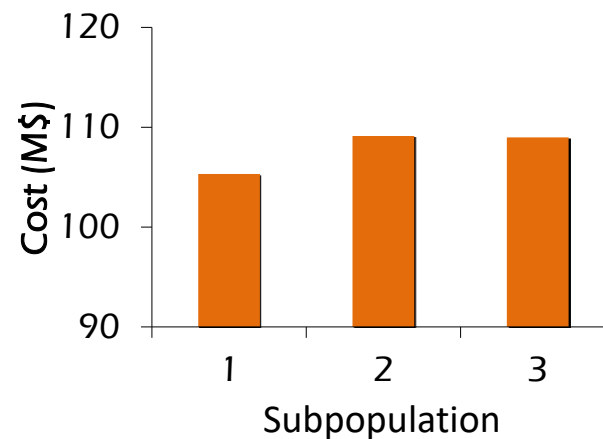
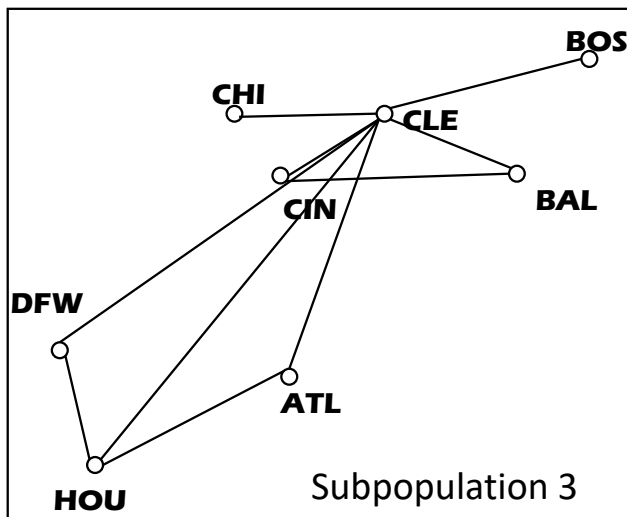
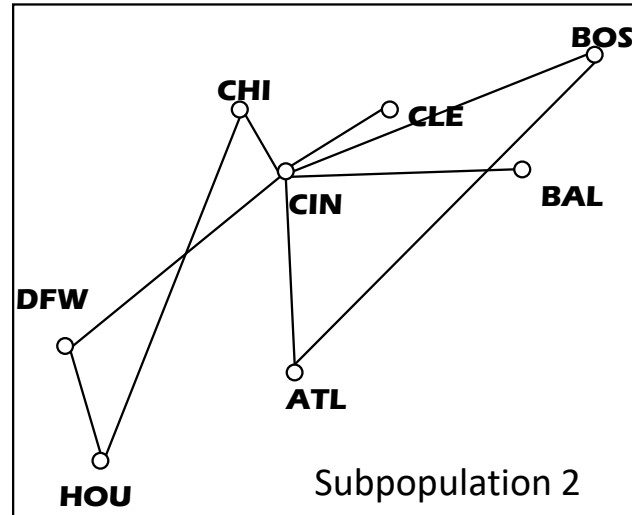
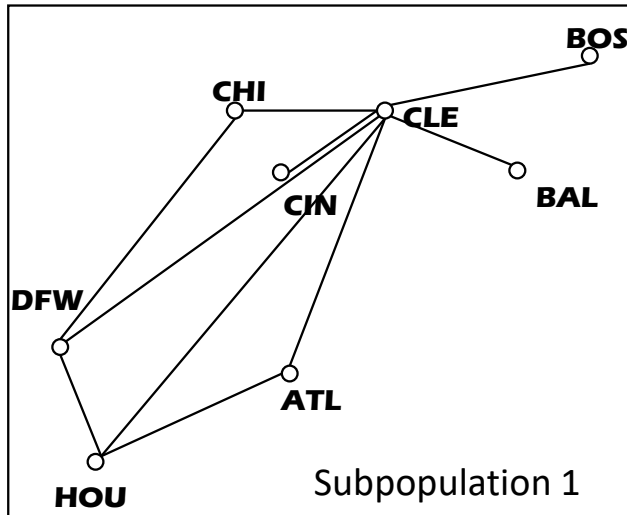
Eighteen-stop alternative solutions



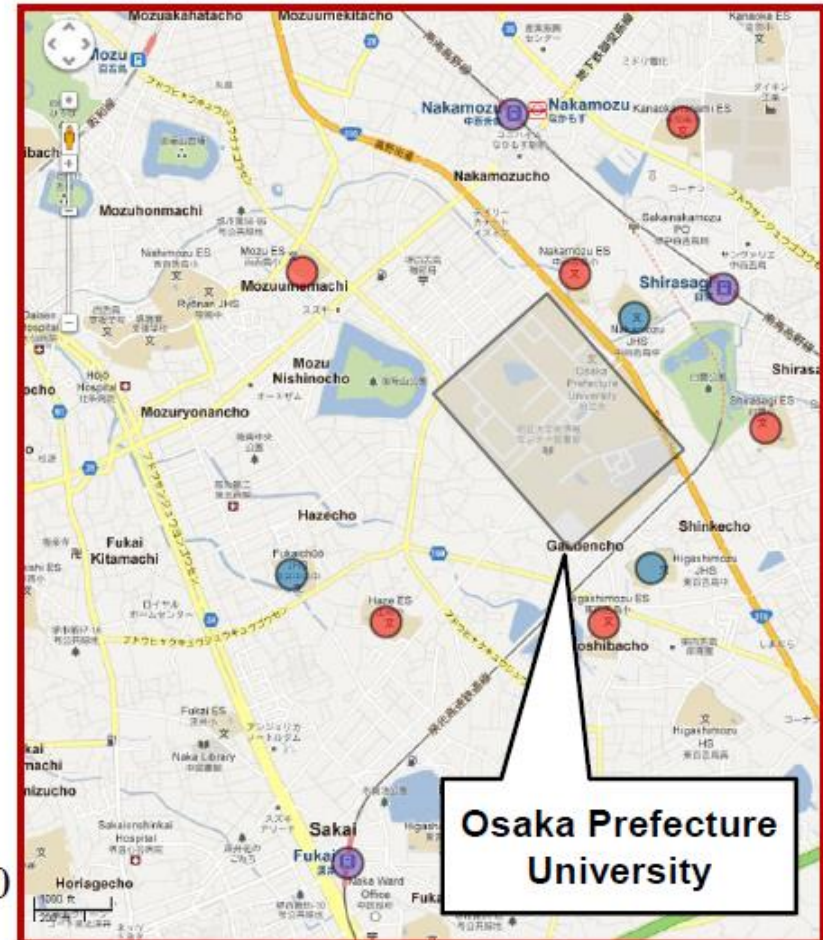
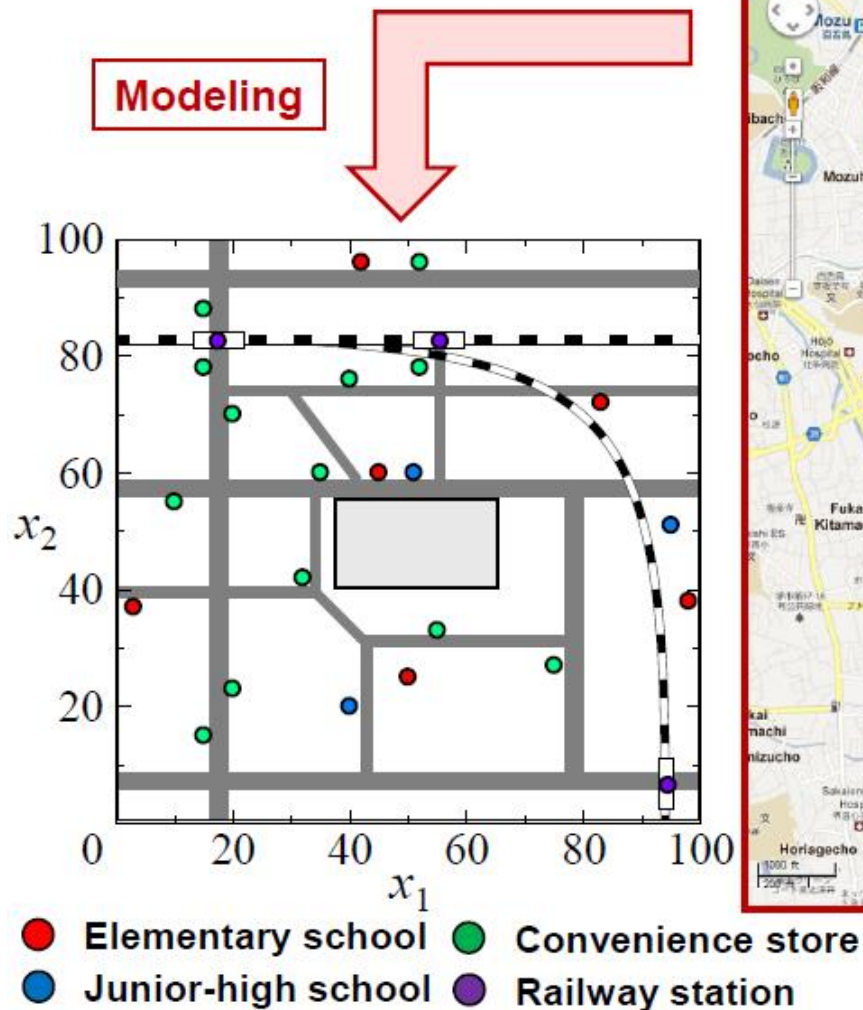
Distinct sets of non-dominated solutions



Seventeen-stop alternative solutions



Where should Osaka Prefecture University be located?



OFU – Problem Formulation

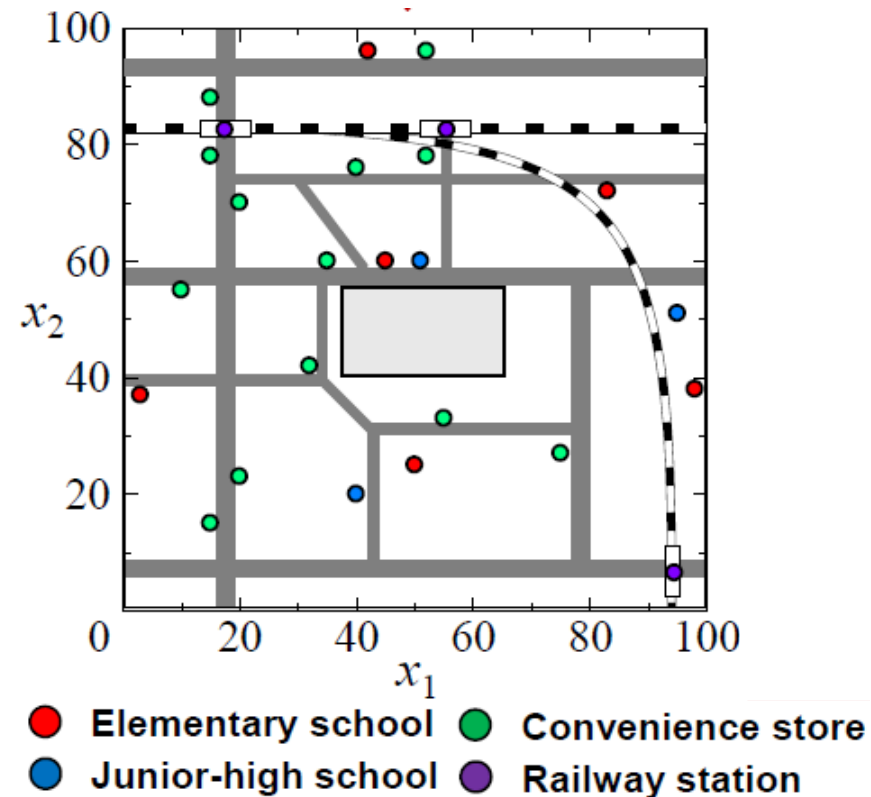
2 decision variables and 4 objective values

$f_1(x_1, x_2)$ = min distance to the nearest elementary school

$f_2(x_1, x_2)$ = min distance to the nearest convenience store

$f_3(x_1, x_2)$ = min distance to the nearest junior-high school

$f_4(x_1, x_2)$ = min distance to the nearest railway station

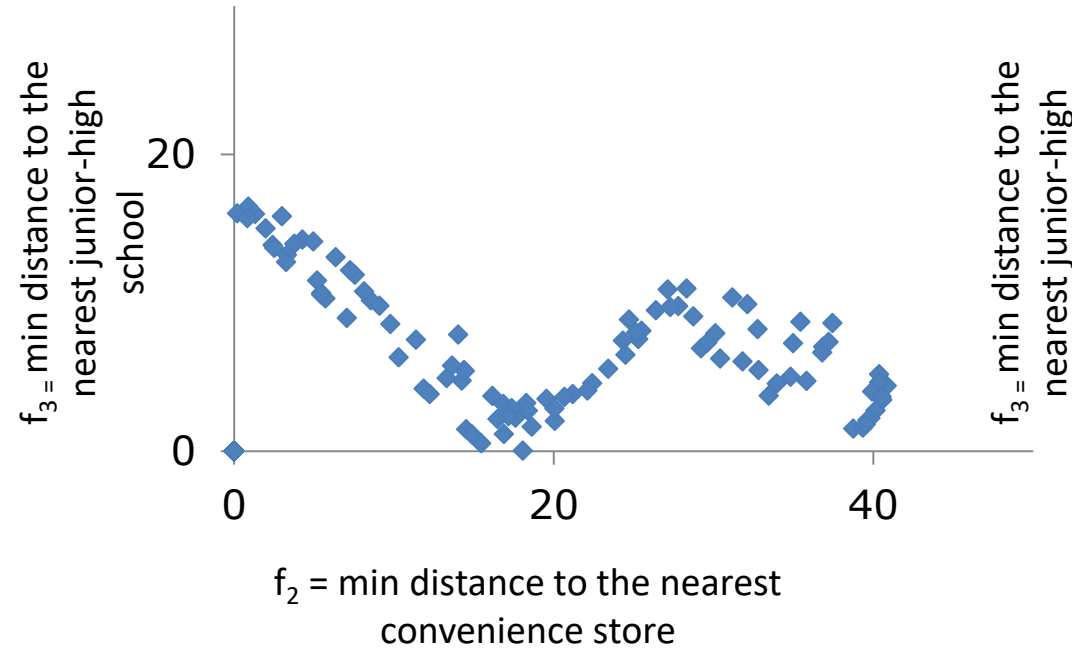


OFU – Algorithm settings

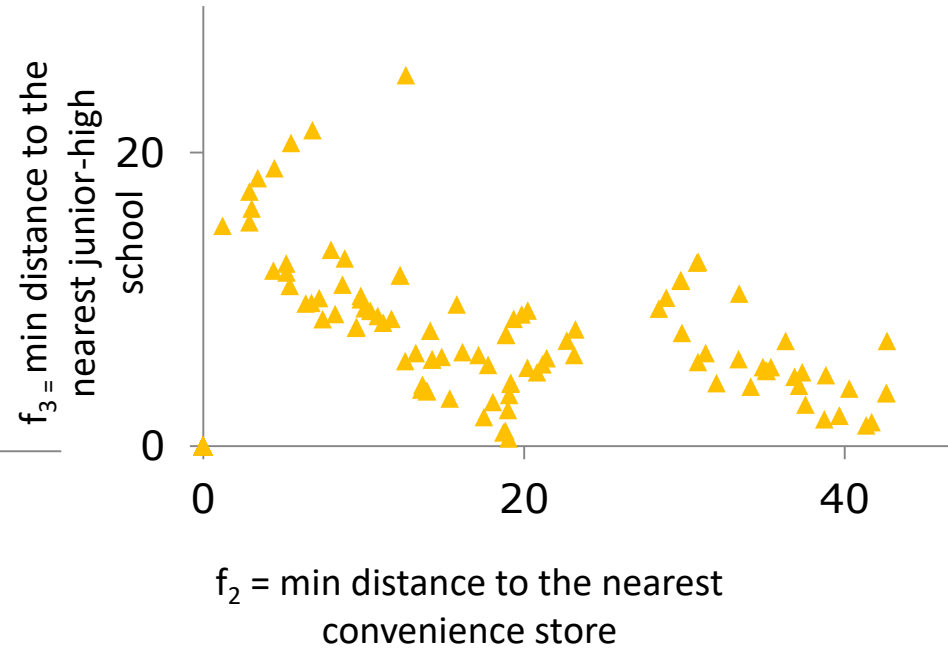
Parameter	Setting
Population Size	100
Subpopulations	2
Generations	100
Mutation	1%
Clusters	5
Target	95%

Results - Objective Space

Subpopulation 1

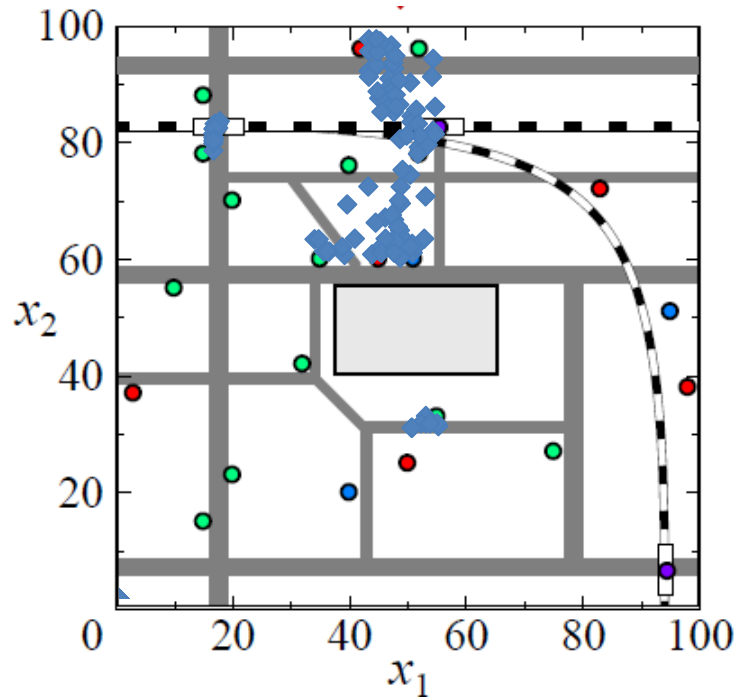


Subpopulation 2

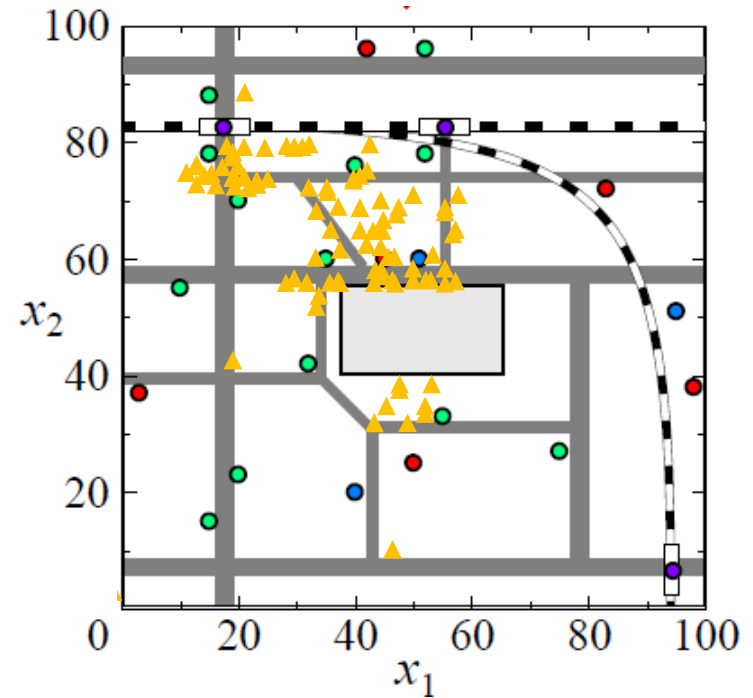


Results - Decision Space

Subpopulation 1



Subpopulation 2



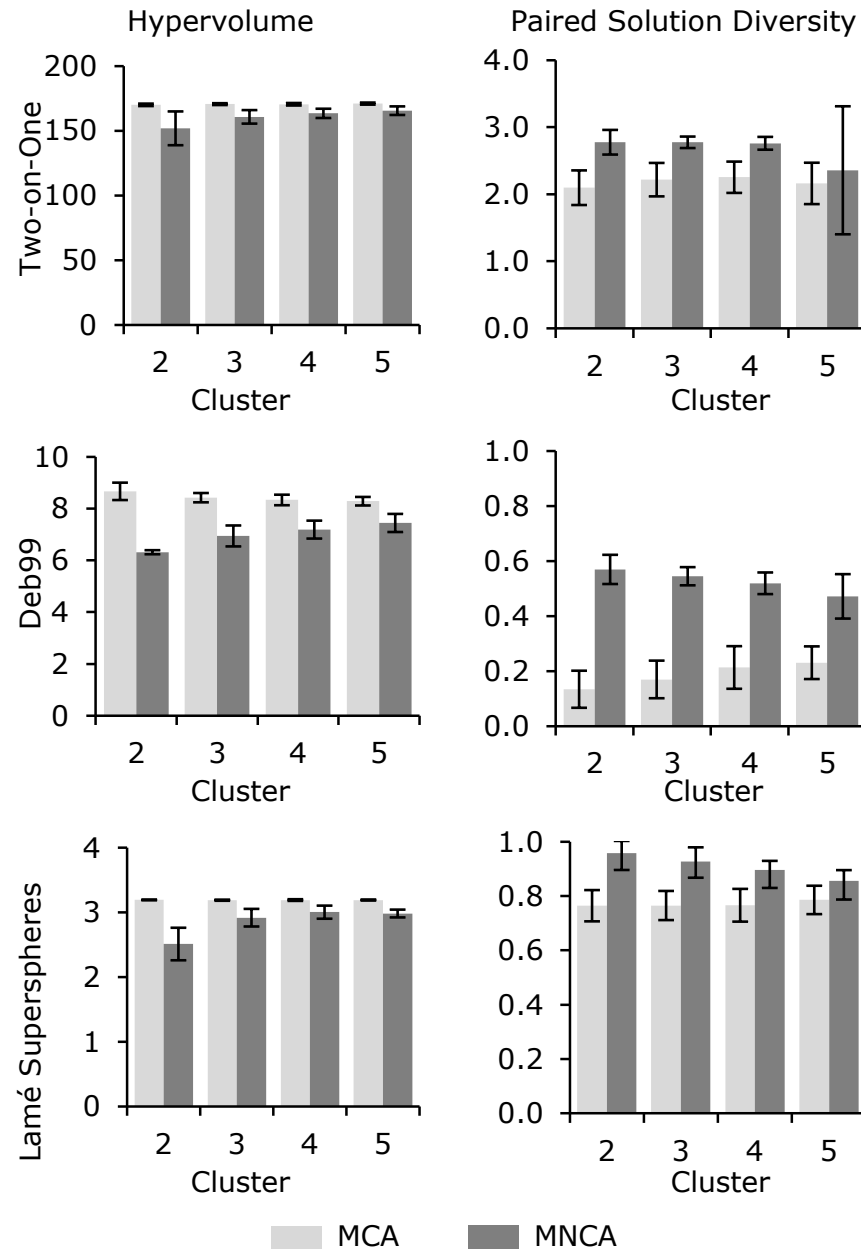
Conclusions

- Results demonstrate the ability of a new algorithm, MNCA, to identify sets of non-dominated solutions for test problems.
- Outperforms state-of-the-art (Niching-CMA) in diversity algorithms for multi-objective problems.
- A new metric to assess diversity among subpopulations was developed.
- MNCA maximizes diversity in decision space while identifying complete alternative Pareto fronts.

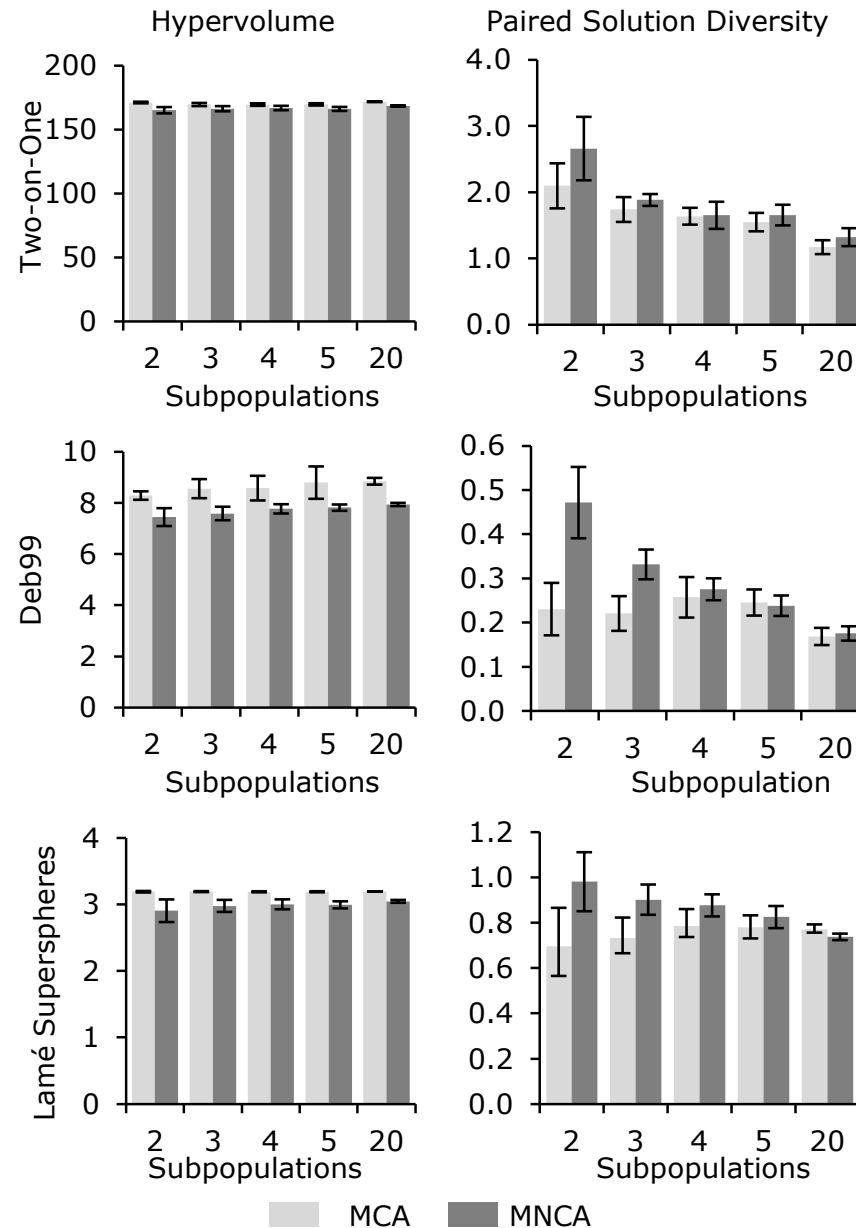
Thank you for your Attention!



Number of Clusters



Number of Subpopulations



Targets

